

LVD Timing Diagram Correction

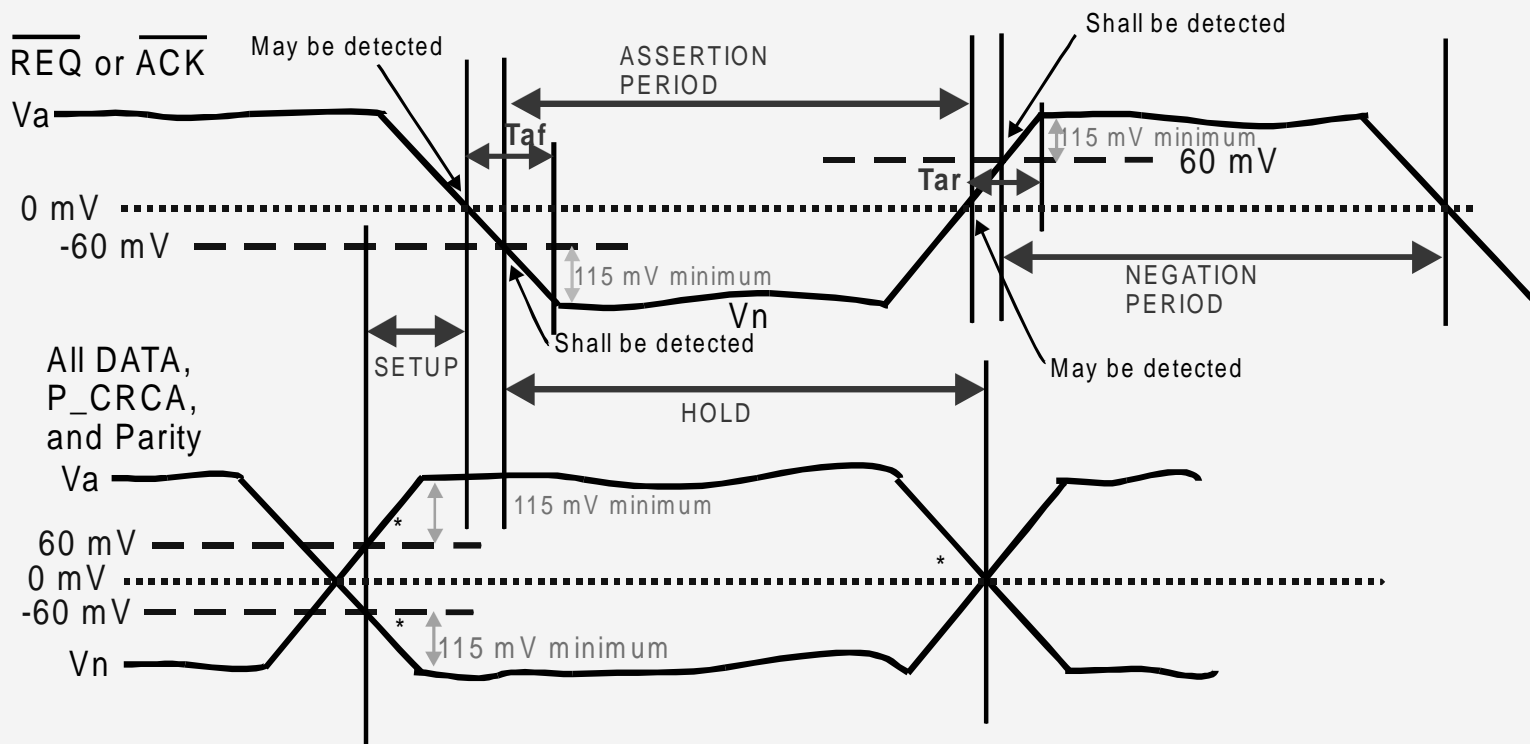
SPI-3R3 Figure 44 & 45 correction

Text Correction

Driver Level Issues

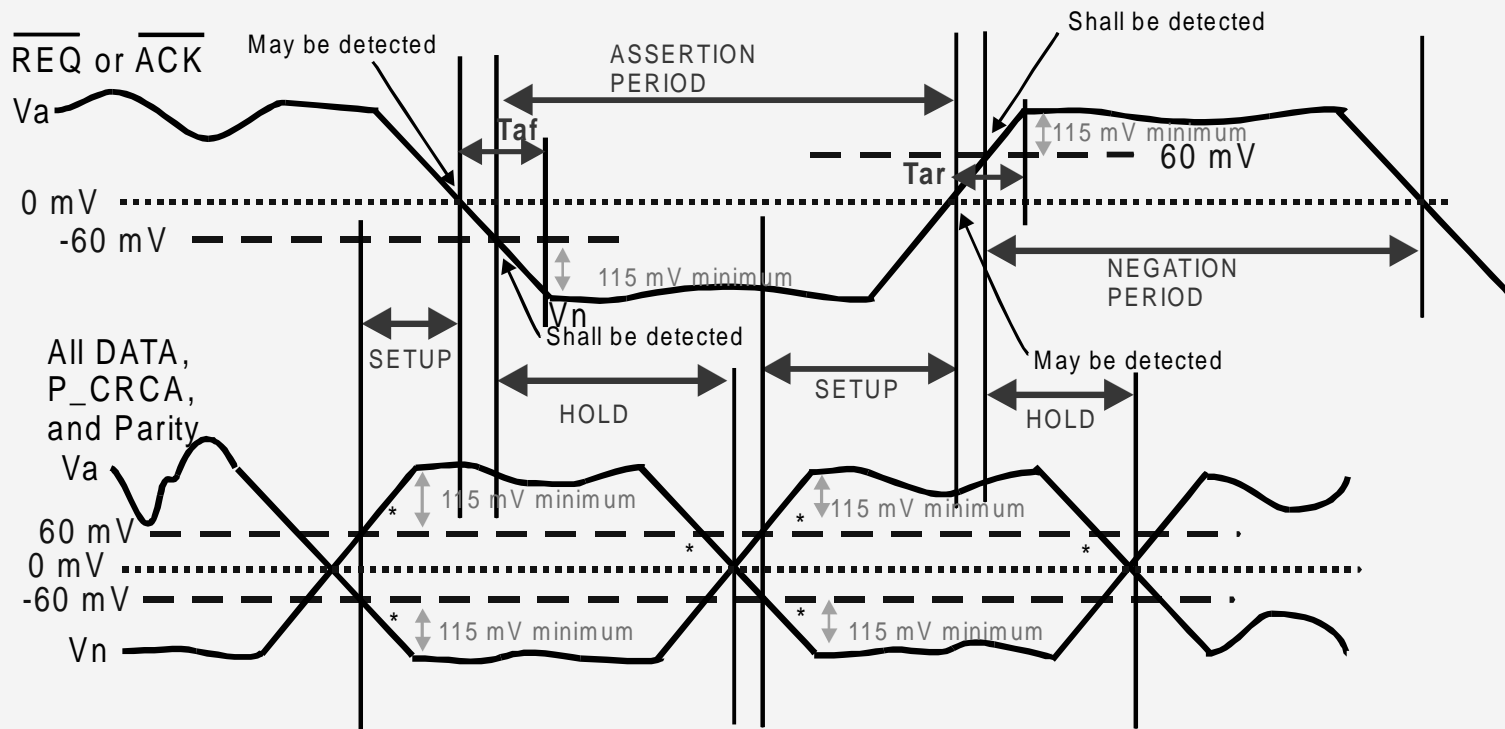
Receiver Requirement

- The receivers require over drive to switch fast enough to not have skew problems.
- The receiver overdrive is not a function of the previous voltage, but a fixed 115 mV over the 60 mV AC threshold.
- AC measurement may switch is not 60 mV, it is 0 mV.
- No Receiver rise - fall time requirements specified



* Use the crossing that yields the shorter SETUP and HOLD Time
 V_a or V_n must over drive the 60 mV threshold by 115 mV at the leading edge of the transition.
 V_n = Negated Signal
 V_a = Asserted signal
 Differential voltage signals in all Cases
 T_{af} and T_{ar} must be less than 3 ns and receiver will only deliver one state change signal reversals may occur during the period.

Proposed changes to the LVD ST Timing Diagrams
 -Figure 44



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Differential voltage signals in all Cases

T_{af} and T_{ar} must be less than 3 ns and receiver will only deliver one state change signal reversals may occur during the period.

Proposed changes to the LVD DT Timing Diagrams

-Figure 45

Text Correction

- 9.2.3 ST Timing & 9.2.4 DT Timing second paragraph second sentence
 - With the maximum assertion level of V_A it requires a signal that crosses the zero differential level by at least $0,25 \times V_A$ (but at least by 60 mV in all cases) to guarantee detection of a negation for fast signals.
 - Change to: Receivers require at least 115 mV over the 60 mV AC threshold or 175 mV to guarantee detection with the proper receiver switching time.

System Loss, Driver Requirements

- The previous system requirement was 115 mV
 - 60 mV AC threshold plus 55 mV for crosstalk
 - Receiver requirements of 175 mV
 - The system test show a 50% reduction in signal level on a loaded bus.
 - Minimum drive level of 400 mV is required, the current level is 270 mV.

Annex A Changes

- Table A.1
 - V_a Max Min -1 V, -175 mV
 - V_n Min 175 mV, Max 1 V
 - Remove the third line of the table
 - Note 1 -These limits allow 60 mV base A.C. level and a maximum 55 mV for crosstalk and other non-common mode noise.
Changes to: These limits allow 60 mV base A,C, level and a minimum of 115 mV overdrive.

Annex A Continued

- A.2.1 second paragraph second sentence
 - This value shall be large enough that, after allowance for attenuation, reflections, and differential noise coupling, V_S is at least +60 +175 mV at the device connector to the LVD bus.

A.2.1 Paragraph 4

- With the test circuit of figure A.1 and the test conditions V_1 and V_2 in table A.2 applied, the steady-state magnitude of the differential output voltage, V_S , for an asserted state (V_A), shall be greater than or equal to 270 400 mV and less than or equal to 780 mV. For the negated state, the polarity of V_S shall be reversed (V_N) and the differential voltage magnitude shall be greater than or equal to 260 400 mV and less than or equal to 640 mV. The relationship between V_A and V_N specified in table A.2 and shown graphically in figure A.2 shall be maintained.

Annex A Continued

- Table A.2
 - Change all the minimums to 400 mV
- Figure A.2
 - Move the lower part of the shaded area to 400 mV on both axis.