# Back to Reality

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#### SPI-2 Working Group 4/18/97



## Issues

**First Pulse Magnitude** 

Whose Fault is it?

Asymmetric/Symmetric Current Drive Which is Better?

**Tolerances of Current Sources** 

Can they Work?

**Active Bias Terminators** 

Why we Need Them?

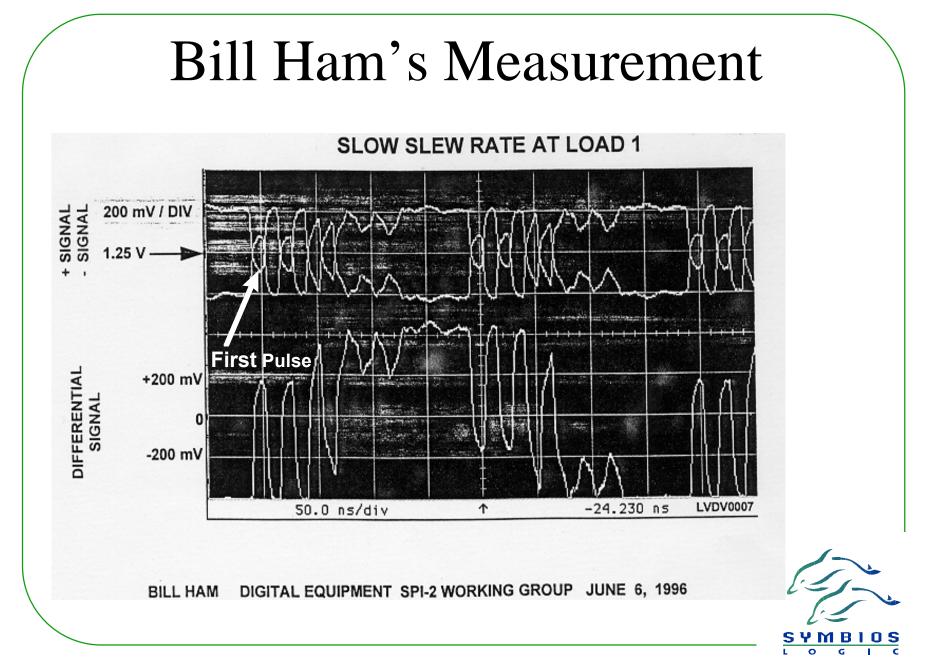


# Do you Remember These?

Picture by Bill Ham, SPI-2 Meeting, June 6, 1996

First Pulse Distortion Symmetric Driver, 150W Symmetric Terminator Fully Loaded Cable Advanced Warning





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# Whose Fault is it?

¿ Current Source Drive ?

¿ Active Terminator ?

¿ Asymmetric Driver ?

¿ Symmetric Driver ?

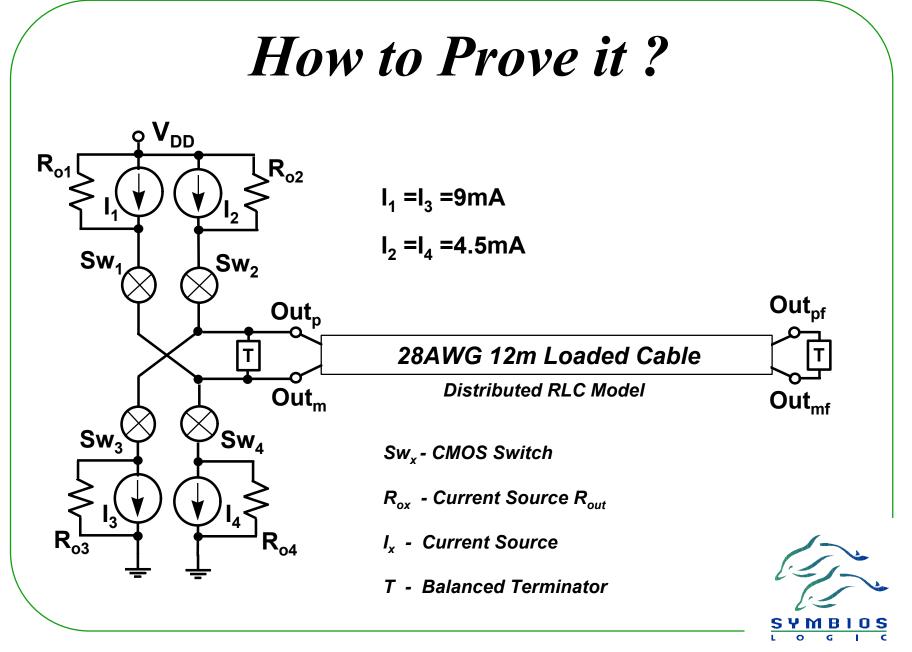


# Whose Fault is it?

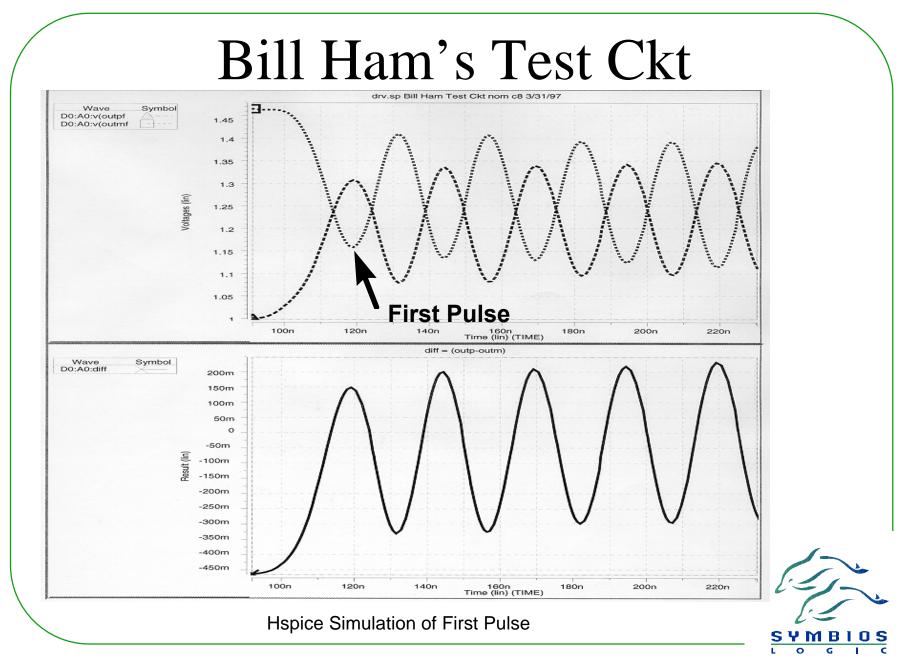
(None of the Above)

#### It s the TRANSMISSION LINE





T10/97-159 r0



# Which is Better?

Asymmetric Current Driver or

#### Symmetric Current Driver ?

Measured data - verified by simulation results proves that symmetric drive offers <u>no advantage</u>

over present asymmetric drive



# Active Terminator Benefits

Built-in Bias for Fail-Safe Operation Common-Mode Drive / Sink Current Controlled Impedance Low Capacitance Simpler Receiver Circuitry Even without Bias, Active Terminator Needed



## Why Terminator Bias?

**Provides Fail-Safe Operation** 

**Symmetric Signal is Achievable** 

**Balanced Receiver - Low Skew** 

**No Complex Dual Receiver** 



# **Receiver Sensitivity**

Typical V<sub>in DIFF</sub> = 400mV (No Load) Worst Case V<sub>in DIFF</sub> = 60mV (Loaded Cable) Worst Case Process, Temp & Supply Voltage Low Skew Critical



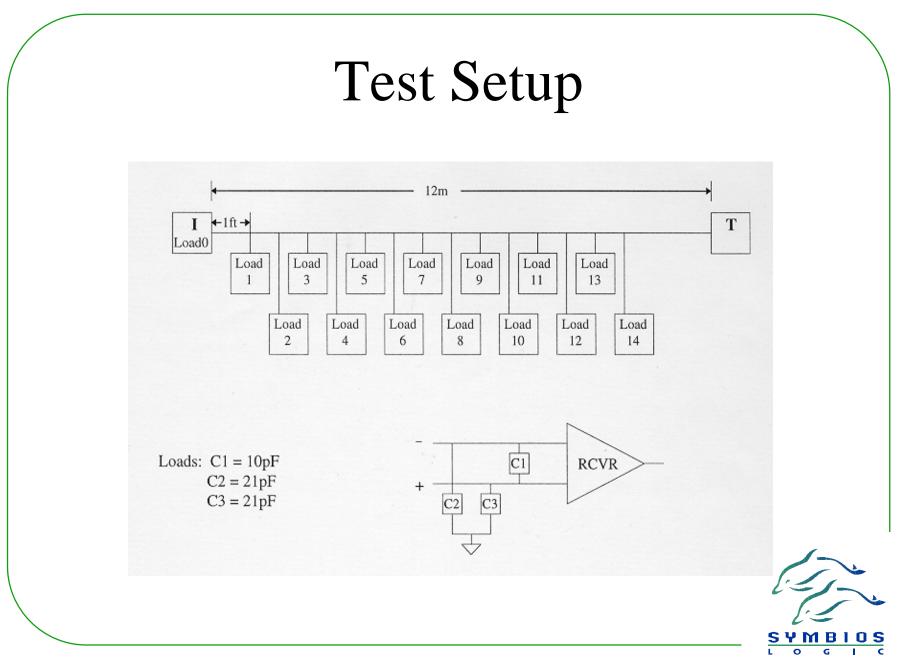
# Current Source Drivers Issues

#### **Current Mirror Match**

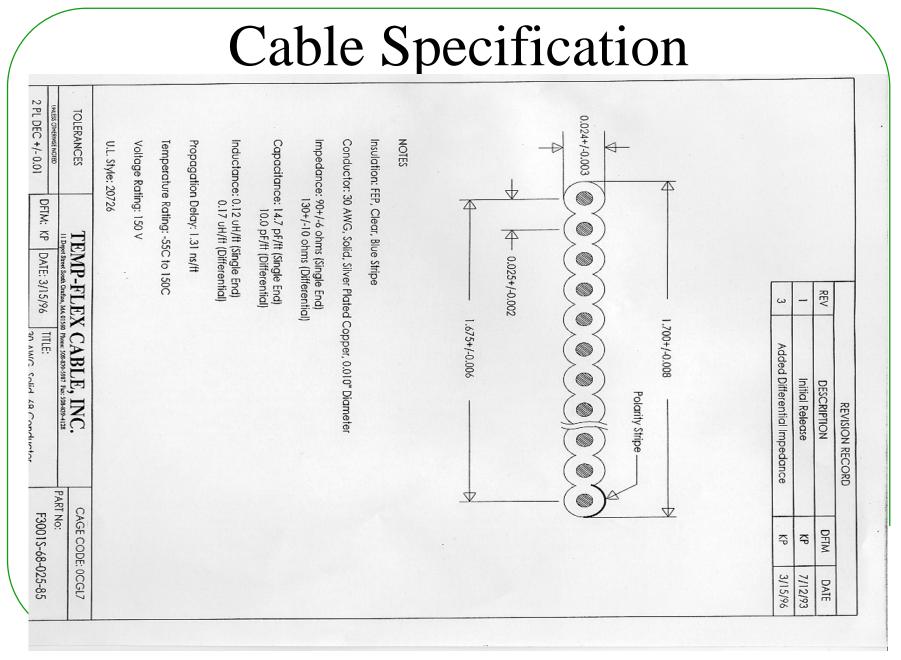
I<sub>DP</sub> versus I<sub>DN</sub> Match

Identical Challenge for Symmetric or Asymmetric Drivers

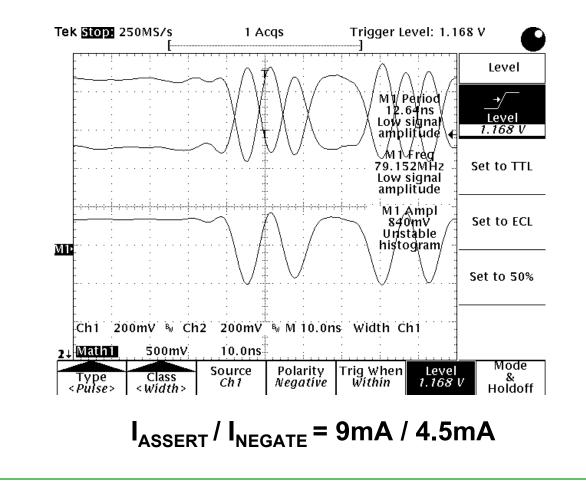




#### T10/97-159 r0

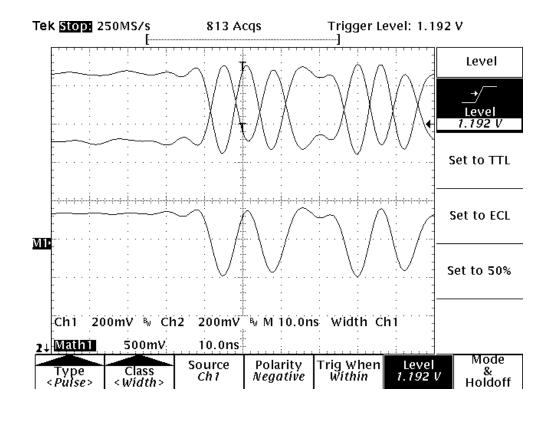






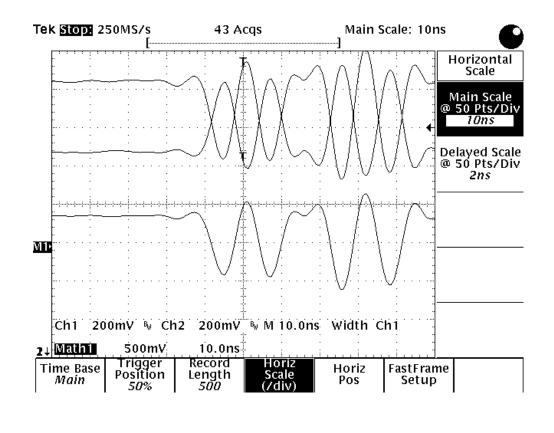




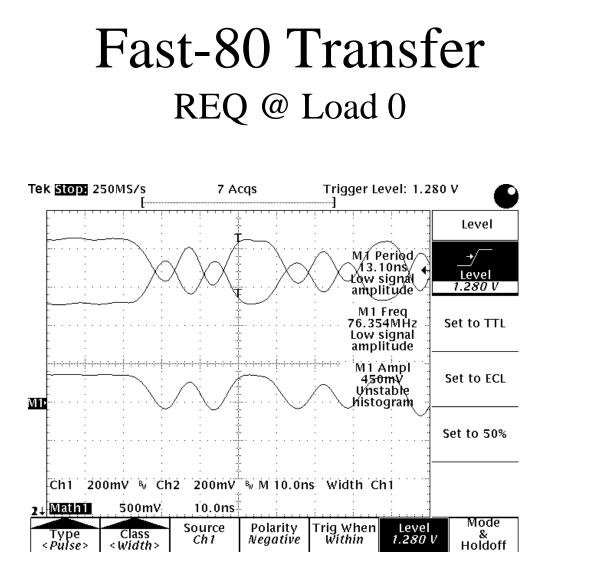




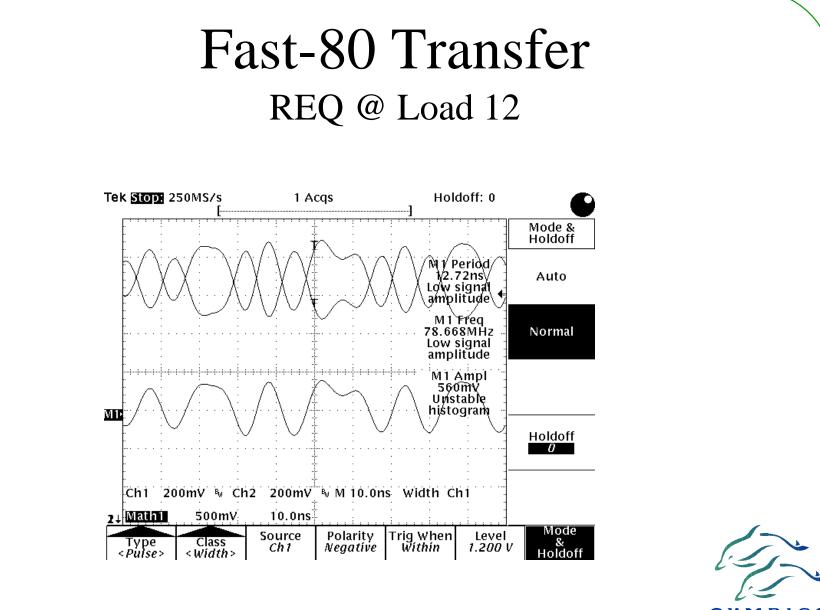
### Fast-80 Transfer @ Driver ACK - 15 Loads

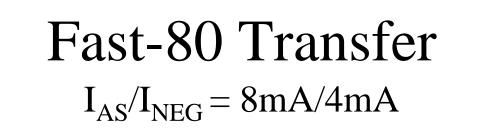


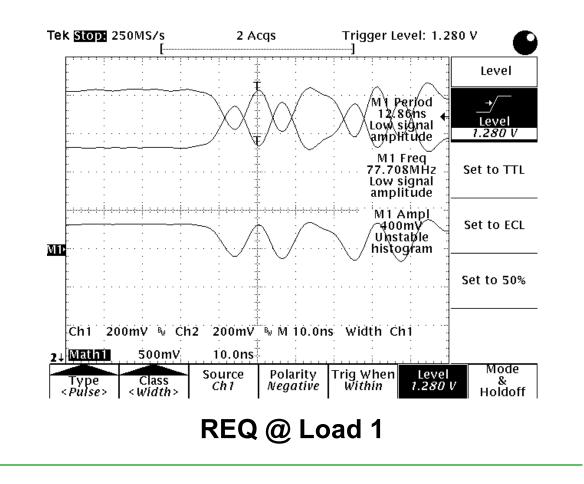




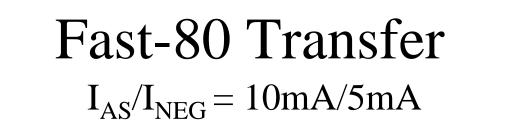


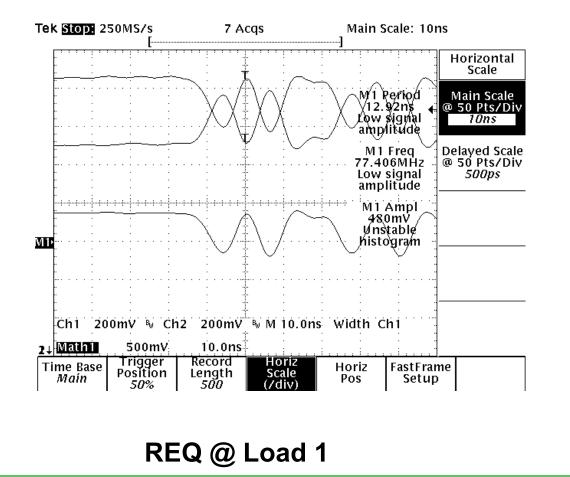














## LVD Power

<u>Asymmetric Drive</u>:  $V_{diff}$ =400mV,  $Z_{o}$ =120 $\Omega$  $V_{BIAS}$ =120mV

lassert = 8.667mA ⇒ P<sub>D</sub> =(3.3-0.4)V \* 8.667mA = 25.13mW

Inegate = 4.667mA  $\Rightarrow P_{D} = (3.3-0.4)V * 4.667mA = 13.53mW$ 

Total Average Power = 19.33mW



## LVD Power

**Symmetric Drive**:  $V_{diff}$ =400mV,  $Z_{o}$ =120 $\Omega$ 

lassert = 6.67mA ⇒ P<sub>D</sub> =(3.3-0.4)V \*6.67mA =19.33mW

Inegate =6.67mA ⇒ P<sub>D</sub> =(3.3-0.4)V \*6.67mA =19.33mW

Total Average Power = 19.33mW



# Symmetric Driver ?

No Advantage in Performance No Fail-Safe Operation Identical Power Dissipation Increased Receiver Complexity



# **Beyond Fast-80**

Cable Length Number of Loads Receiver Sensitivity Cable Media Protocol Issues If Symmetric Driver has Merit Beyond Fast-80, the Transition Need Not to be Disruptive

