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To: X3T10 Membership

From: Greg Alvey - Solution Technology

Subject: Proposal for New SCSI-3 "AutoSense" Message

# Discussion:

CAM (Section 7.7) discusses AutoSense, but in a way that only saves the upper layers of the system (application client) from having to do the work of building and issuing a REQUEST SENSE command. This still involves another "middle" layer on the host side having to intercept the status (i.e. CHECK CONDITION), building a REQUEST SENSE command, connecting to the faulted device to issue the REQUEST SENSE, returning the sense data, and disconnecting again. This does nothing to reduce overhead on the bus itself.

This proposal is intended to provide a way to reduce bus overhead by delivering the sense data during the same connection as the original faulted command.

AutoSense Data (Sense data delivered automatically) can be returned during the same connection as the faulted command by adding support for one two-byte message, "AUTOSENSE DATA FOLLOWS".

# Purpose:

To reduce overhead required to retrieve Sense Data from parallel SCSI devices. This may also apply to other types of physical interconnect systems.

Attachments:

Attachments are provided for proposed changes to SIP, SAM, & SPC.

### Proposed changes in SIP: Message Section - Add the following:

# X.X.X AUTOSENSE DATA FOLLOWS

The AUTOSENSE DATA FOLLOWS message (see table xx) is sent from the target role agent to the initiator role agent, immediately following a CHECK CONDITION or COMMAND TERMINATED status, and requests that the initiator role agent prepare to accept sense data related to the currently faulted command. The target role agent then sends the sense data associated with the faulted command followed immedately by the TASK COMPLETE message.

Any ACA which may have been generated for the faulted command is cleared when the sense data has been transferred, according to the AutoSense rules (see SCSI-3 Architecture Model).

The target role agent shall only use this message for tasks where the Enable AutoSense (EAS) bit has been set to one in the Control byte of the current CDB (see SCSI-3 Architecture Model - Section 5.1.2).

An application client can determine whether a device server implements this message by examining the (ASense) bit in the standard INQUIRY data (see SCSI-3 Primary Commands Standard).

The format of the message is shown below:

	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
byte 0	Message code (25h - proposed)							
byte 1	Number of Sense Data bytes (following)							

AutoSense data follows message format

# The value in the "Number of Sense Data bytes" field is the number of data bytes that will be transferred immediately after this message.

The contents of the sense data bytes are identical to what would be transferred if a REQUEST SENSE command were issued for the currently faulted command.

### Proposed changes in SAM

SAM - Control Byte (Section 5.1.2) - Add the following:

## Change in Control Byte of CDB

	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
byte n	V	S	Rese	erved	EAS	NACA	Flag	Link

The EAS (Enable AutoSense) bit is used to control the rules for delivering sense data related to an ACA condition caused by the command. If the EAS bit is one, the device server may use the AutoSense rules (see clause 5.6.4.2) The ability to support a Enable AutoSense value of one is indicated in standard INQUIRY data.

Proposed changes in SPC

INQUIRY command - Section 7.5.1

Add the AutoSense (ASense) bit to the Standard INQUIRY data format as shown below:

	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
byte 3	AERC	TrmTsk	NormACA	ASense		Response	data format	

The AutoSense bit (ASense) of one indicates that the device server supports setting the EAS bit to one in the Control Byte of the CDB (as defined in SAM). An ASense bit of zero indicates that the device server does not support setting the EAS bit to one.

The following is what AutoSense MIGHT look like on some SCSI bus analyzer.

Bus Free Detected		
Arbitration Start	7	
Arb win	7	
—	(Atn Asserted)	ATN
Selection Start	7 4	ATN
Selection Complete		ATN
-	(Atn Negated)	ATN
Message Out	CO	
Command Out	08 00 01 00 01 08	(Enable AutoSense)
Data In	00 01 02 03 04 05	
	06 07 08 09 0A 0B	
	OC OD OE OF 10 11	
Status In	02	(Check Condition)
Message In	25	(AutoSense Follows)
Message In	12	(18 bytes of Sense Data)
Data In	70 00 02 00 00 00	-
	00 0A 00 00 00 00	
	18 01 00 80 00 85	
Message In	00	
Bus Free Detected		