# A Proposal for Command Overlap and Command Queuing for ATA Devices

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### 1 Introduction

This document describes a method for supporting command overlap and command queuing for ATA devices. The goals for the development of this method were:

- Simplest possible protocols to implement.
- Ability to operate on the same cable with legacy devices (i.e., ATA-2 and ATAPI devices).
- Best possible future performance.

As a result, no effort was made to preserve existing hardware, firmware or software. Choices were made to provide the simplest, least overhead protocols.

A device implementing this method shall power-up in legacy mode and behave as defined in the ATA-2 specification today. The host may then determine the capabilities of the attached devices and enable the overlap and queuing functionality, if desired.

The protocols are designed to require the minimum possible overhead when both devices on the bus implement the overlap and queuing functionality and allow host DMA engines to provide high performance with minimum hardware.

## 2 Configurations Supported

Three configurations are supported by this proposal.

## 2.1 Legacy Configurations

Since the devices implementing this new functionality power up in legacy mode, they may be operated in legacy mode if desired. Therefore, a configuration may be as shown in Figure 1. In this configuration one or both of the devices may be capable of command overlap and queuing but a legacy host will operate them as shown. They operate just as ATA devices operate today where a command on one device is executed completely before a command can be issued to the other device.

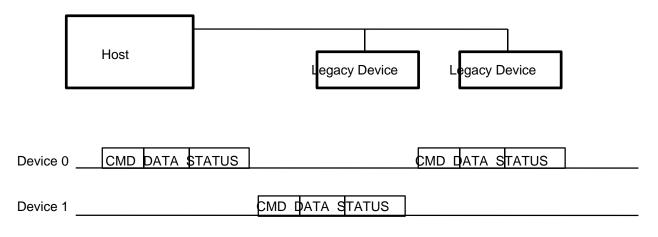


Figure 1 - Legacy Configuration

## 2.2 Mixed Configurations

The mixed configuration allows one device on the bus to behave as a legacy device while the other device is operating in overlapped/queuing mode as shown in Figure 2. This allows a host that is capable of supporting overlap/queuing to make use of the functionality even when a legacy device incapable of the functionality is present. Figure 2 shows how commands for the two devices may be interleaved when Device 0 is the Legacy Device and Device 1 is the Overlapped Device. The overlapped device may in fact be configured as either Device 0 or Device 1 in this configuration.

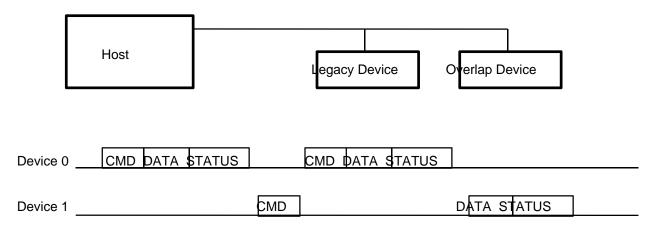


Figure 2 - Mixed Configuration

## 2.3 Overlapped Configuration

The overlapped configuration can occur when the host and both devices are capable of overlapped functionality as shown in Figure 3. This proposal is designed to provide minimum overhead and maximum performance with this configuration. As shown by the first command to each device, the issuing of a command to a second device can be placed between the issuing of a command to the first device and the transfer of the first device data. If the device supports queuing as well as overlap, a subsequent commands may be issued to a device before a first command completes as shown by the second and third commands to device 0. In addition, if the data transfer is made in DMA mode, the data transfer may be completed in multiple data transfers instead of a single transfer as shown.

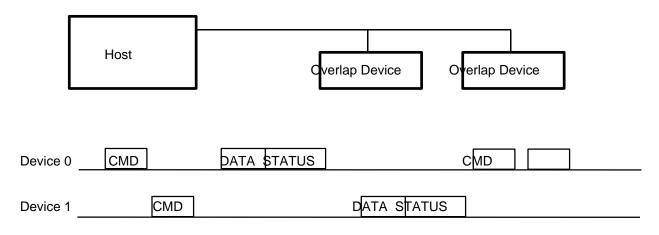


Figure 3 - Overlapped Configuration

## 3 Overlap/queuing Functional Issues

To implement command overlap and queuing a number of functional issues must be addressed. This clause describes each of these issues and defines solutions to them.

## 3.1 Register Ownership

Under the ATA specification today, register ownership is very clear. When a command is issued to a device, the device maintains a state with either BSY or DRQ asserted until the command is completed. During this time, the busy device owns the register set and the host may not write registers to either device without dire consequences. When the device has completed the command (neither BSY nor DRQ set), the host owns the registers and may write the registers for either device.

For devices implementing overlap/queuing the rules change slightly. When a command is issued to such a device BSY is asserted as in the legacy case. If the command is a non-data transfer command, BSY remains asserted until the command completes but if both devices support overlap, the host may select the other drive as soon as the command has been written. If the command is a data transfer command, the device sets BSY, inhibits writing of its command block registers, saves the contents of the applicable command block registers, and then clears BSY. If both devices support overlap, the host may select the other device as soon as the command has

been written. If the device supports queuing, the host may issue a second command as soon as BSY is cleared.

If the configuration is a Mixed Configuration, the host must obey the rules that each device expects. That is, if a command is issued to the legacy device, that legacy device own all registers until that command completes. The host may not access the other device. If the host issues a command to the overlapped device, the host may select the legacy device and issue it a command as soon as the command to the overlapped device has been issued.

### 3.2 Device Selection

Legacy devices today are selected by the host writing the DEV bit in the Drive/Head register. Since this register is owned by a device with BSY or DRQ set, the host is prohibited from selecting the other device when one device is in the process of executing a command.

In a legacy configuration, a device capable of command overlap/queuing is left in legacy mode and selected just as in legacy mode.

In a mixed configuration, a device capable of overlap queuing will be placed in Overlap/DRVsel mode. In this mode, the device is selected just as in legacy mode. Since this device will clear its BSY bit as soon as the command parameters have been saved on a data transfer command, a host may then select the legacy device and execute a command while the overlap device is working on its data transfer command.

In an overlapped configuration where both devices are in overlap mode, both devices are placed in Overlap/CSsel mode. In this mode, selection is accomplished by a redefinition of the CS0- and CS1- signals. Table 1 shows both the legacy and overlapped/CSsel addressing.

Table 1 - Addressing for CS device selection							
Add	ress	Registe	rs Selected				
CS0-	CS1-	Legacy Mode	Overlap/CSsel select mode				
Ν	Ν	Not used	Device 0 - Control Block				
Ν	А	Device 0/1 - Control Block	Device 1 - Control Block				
Α	Ν	Device 0/1 - Command Block	Device 0 - Command Block				
Α	А	Not used	Device 1 - Command Block				
Key:							
A = sig	nal asse	rted, N = signal negated					

Clause 4.2 describes the protocol for entering and leaving these modes.

## 3.3 Interrupt Reporting

Today, there is only one INTRQ signal. It is not sharable so that a device can only assert INTRQ when it is selected by the DEV bit. When placed in Overlap/DEVsel mode, a new device implementing this function will continue to use the INTRQ signal as in legacy mode only asserting the signal when selected. When in Overlap/CSsel mode, Device 0 will interrupt using INTRQ; Device 1 will interrupt using a redefined IOCS16/INTRQ1 signal. These interrupts may be asserted at any time regardless of whether or not the device is currently selected. As can be seen, this allows the devices to notify the host that service is required regardless of current selection and allows the host to know exactly who is interrupting.

## 3.4 Command Queue Tags

The Identify Device info returned by a device capable of overlap/queuing operation will contain a four bit queue depth field. If this field is 0h, the device does not support queuing. If the field contains any other value, this value plus one indicates the depth of queue supported up to a maximum queue depth of sixteen. Any tag issued by the host with a tag number greater than this value will cause the command to be aborted.

To support queue tags, all registers are defined as being sixteen bit registers just as the Data register is today. The upper byte of the Command, Status, and Alternate Status registers are as shown in Table 2. The upper byte of the remaining registers are reserved and shall be written as all zeros and ignored on read. In particular, the upper byte of the Cylinder Low and Cylinder High registers is reserved for future address space expansion.

When issuing a data transfer command to a device in overlapped/queuing mode, the upper byte of the Command register will indicate that this is an overlapped command and provide the queue tag number for this command.

When a queued device interrupts for service for a queued command, the tag for the command requiring service will be contained in the upper byte of the Alternate Status and Status register.

All queued commands shall be simple queued commands, no priority is implied.

Register	15	14	13	12	11	10	9	8	
Command	OVL	r	r	r	TAG(3:0)				
Status or	CC	r	r	r	TAG(3:0)				
Alternate Status									
Where:									
OVL = one indicates an overlapped command.									
TAG(3:0) = Queue tag number for command.									
CC = one indicate	CC = one indicates command complete.								

Table 2 - Upper byte definitio	ns
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## 3.5 Host Synchronization

Command overlap and command queuing make the use of an intelligent DMA engine in the host an attractive added feature to improve performance particularly with a multithreaded operating system. However, with such an intelligent DMA engine, the accesses to the devices by the DMA engine and the host device driver must be synchronized. That is, the device driver may not access the devices while the DMA engine is in the process of transferring data to/from a device, and the DMA engine may not transfer data while the host device driver is accessing registers to issue a command or check status.

The following is an example of how this synchronization may be accomplished. The DMA engine will have a register accessible by the host. The ATAREQ bit in the register will be writable by the host. When the host device driver wishes to access a device to issue a command or read status, the host will set the ATAREQ bit to one.

If the DMA engine is not currently transferring data to/from a device, it will set the ATAACK bit to one. When both the ATAREQ and ATAACK bits are one, the host device driver may access a device and the DMA engine Shall not access a device.

If the DMA engine is in the process of transferring data to/from a device when the ATAREQ bit is set, it will complete the transfer and then set the ATAACK bit to one.

When the host device driver has completed the required device accesses, it will set the ATAREQ bit to zero. The DMA engine will immediately set the ATAACK bit to zero, and the DMA engine may now access a device.

In this way, accesses by the DMA engine and the host device driver are synchronized.

## 4 Protocols

The following clauses describe the protocols for operation of devices in overlapped/queued mode.

### 4.1 Power-up/ Reset Protocol

Devices supporting overlap/queuing functionality shall power-up in legacy mode following the currently specified power-up protocol. These devices shall remain in legacy mode until commanded to enter overlap mode and shall be capable of full normal legacy operation.

## 4.2 Entering/Leaving Overlapped Mode

To place a device into overlapped mode, the host issues a SET FEATURES command with the set overlapped mode code in the Features register. This code indicates the device should enter overlapped mode and indicates whether DEV or CS signals should be used for selection.

Once placed into overlapped mode, the device shall remain in overlapped mode until:

- a SET FEATURES command is received removing the device from overlapped mode.
- a hardware reset is received.
- the device is powered-down.

These events also cause any existing queue to be aborted.

A software reset does not remove the device from overlapped mode but does abort any existing queue.

An overlapped device in a mixed configuration is placed into Overlap/DEVsel mode. When BSY is set to one at the completion of the SET FEATURES command, the device is in Overlap/DEVsel mode and device selection is still accomplished via the DEV bit.

In a overlapped configuration both devices are placed into Overlap/CSsel mode. This is accomplished by the following protocol.

The host selects Device 1 by writing the DEV bit to one. The host then issues a SET FEATURES command to Device 1 to set Device 1 into Overlap/CSsel mode. Note that these register writes are accomplished in legacy mode a shown in the legacy column of Table 3.

When Device 1 sets the BSY bit to one at the completion of the command, the Device 1 will be in Overlap/CSsel mode and the two devices will be responding to register accesses as shown in the intermediate column in Table 3. The host shall wait 2 msec after issuing the SET FEATURES command and then check the Device 1 BSY by reading at the CS1 and CS0 signals active address.

The host will then select Device 0 by writing to its Device/Head register. Note that Device 1 no longer responds to accesses to that address. The host then issues the SET FEATURES command to Device 0 to place it into Overlap/CSsel mode.

When Device 0 has completed the command and set BSY to one, both devices are in Overlap/CSsel mode and responding to accesses as shown in the Overlap/CSsel mode column of Table 3.

Address		Registers Selected					
CS0 CS1		Legacy Mode	Intermediate	Overlap/CSsel Mode			
Ν	N Not Used		Not Used	Device 0 Control			
Ν	A Device 0/1 Control		Device 0/1 Control	Device 1 Control			
Α	Ν	Device 0/1 Command	Device 0 Command	Device 0 Command			
Α	A A Not Used		Device 1 Command	Device 1 Command			
Key:							
A = signal asserted, N = signal negated							

Table 3 -	Addressing	durina	mode change	е
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To remove the devices from the Overlap/CSsel mode the process is reversed. First, Device 0 is removed from Overlap/CSsel mode by issuing a SET FEATURES command. This returns the two devices in the state shown in the intermediate column of Table 3. When Device 0 has set BSY to one indicating the command is complete, the host issues a SET FEATURES command to Device 1 removing it from Overlap/CSsel mode. The host then waits 2 msec and selects Device 1 via the DEV bit and checks for the setting of BSY to one.

Note that the host may **not** attempt access to the Control block registers of either device when in the intermediate state.

## 4.3 Device Selection

When placed into overlapped mode the device will be instructed whether device selection will be accomplished by use of the DEV bit or the CS signals. In either case, when in overlapped mode a device shall only write from the bus to its command block registers when selected.

### 4.3.1 Selection in Overlap/DEVsel Mode

When configured in a mixed configuration the overlapped device shall be configured as Device 1 and shall be set to Overlap/DEVsel mode. In this state, device selection shall be made via the DRV bit in the Drive/Head register. In this mode, device selection is accomplished just as in legacy mode. However, when data transfer commands are received, an overlapped device in this mode shall clear BSY as soon as the required command parameters have been saved from the command block registers, and therefore, the host may select the other drive as soon as BSY is negated.

### 4.3.2 Selection in Overlap/CSsel Mode

When configured in an overlapped configuration, the overlapped shall be set to Overlap/CSsel Mode. In this mode, device selection is accomplished by the use of the CS signals.

The host may change the device selection via the CS signals when the currently selected device has BSY asserted. It may change the selection via the CS signals when DRQ or DMARQ is asserted but the data transfer has not begun (i.e., no data has been written or read since the assertion of DRQ or DMARQ). However, if DRQ or DMARQ is asserted and data has been transferred since their assertion, the data transfer shall be completed (i.e., DRQ and DMARQ both negated) before selection shall be changed.

### 4.4 Register Accesses

Protocol for register accesses for a device in overlapped mode changes only slightly from that of legacy operation. When BSY or DRQ are asserted, the information returned when reading a register is undefined except for BSY and DRQ. Registers may be written any time BSY is not set. When a non-data transfer command is issued, BSY shall remain set until the command is completed. When a data transfer command is issued BSY will remain set only until the device has saved the command and its required parameters. When not selected, a device shall ignore all register accesses on the bus.

### 4.5 PIO Data Transfers

When a PIO data transfer command is received, the device will set BSY, prevent all register writes, save the command and required parameters, then clear BSY and again allow register writes. If the device supports command queuing, a new command may be written; if the device does not support command queuing, the writing of a second command will cause the first command to abort.

#### 4.5.1 PIO Data Transfers in Overlap/DEVsel Mode

When the data transfer can be accomplished, the device shall assert DRQ and, if selected, assert INTRQ. If the data transfer can be accomplished immediately upon receiving the command (e.g., a write command and a write buffer is available or read command the data is available in the device buffer), DRQ may be asserted before BSY is negated. In this case, the host may chose to execute the data transfer immediately or select the other device.

When the host selects the device that has completed the requested data transfer, the device shall have DRQ clear, ERR asserted if applicable, and INTRQ asserted.

When the host has selected the device and recognized the INTRQ, it shall read the Alternate Status register.

- If the Status register has DRQ set and BSY cleared, the device is ready to execute the data transfer. At this time, the host may either execute the data transfer or select the other device. If the host chooses to transfer the data, the data is transferred using the existing PIO data transfer protocol. The host shall not deselect the device until the data transfer has been completed.
- If the Status register has DRQ and BSY both cleared and CC set, the device has completed the command. This may be an error free completion or a completion with error depending on the state of the ERR bit just as with a legacy device.

#### 4.5.2 PIO Data Transfers in Overlap/CSsel Mode

When the data transfer can be accomplished, the device shall assert DRQ and, if selected, assert either INTRQ or INTRQ1 as appropriate. If the data transfer can be accomplished immediately upon receiving the command (e.g., a write command and a write buffer is available or read command the data is available in the device buffer), DRQ may be asserted before BSY is negated. In this case, the host may chose to execute the data transfer immediately or select the other device.

When the device has completed the requested data transfer, the device shall clear DRQ, assert ERR if applicable, and assert its interrupt, either INTRQ or INTRQ1.

When the host receives an interrupt from a device with a PIO data transfer command outstanding, it shall select the interrupting device using the protocol described above. Note that the host explicitly knows which device asserted the interrupt. The host shall then read the Status register.

- If the Status register has DRQ set and BSY cleared, the device is ready to execute the data transfer. At this time, the host may either execute the data transfer or select the other device. If the host chooses to transfer the data, the data is transferred using the existing PIO data transfer protocol. The host shall not deselect the device until the data transfer has been completed.
- If the Status register has DRQ and BSY both cleared, the device has completed the command. This may be an error free completion or a completion with error depending on the state of the ERR bit just as with a legacy device.

### 4.6 DMA Data Transfers

When a DMA data transfer command is received, the device will set BSY, prevent all register writes, save the command and required parameters, then clear BSY and again allow register writes. If the device supports command queuing, a new command may be written; if the device does not support command queuing, the writing of a second command will cause the first command to abort.

### 4.6.1 DMA Data Transfers in Overlap/DEVsel Mode

When the data transfer can be accomplished, the device shall assert DMARQ and, if selected, assert INTRQ. If the data transfer can be accomplished immediately upon receiving the command (e.g., a write command and a write buffer is available or read command the data is available in the device buffer), DMARQ may be asserted before BSY is negated. In this case, the host may chose to execute the data transfer immediately or select the other device.

When the device has completed the requested data transfer, the device shall clear DMARQ, assert ERR if applicable, and if selected, assert INTRQ.

When the host has selected the device and recognized an interrupt from the device with a DMA data transfer command outstanding, it shall read the Alternate Status register.

- If the device has the DMARQ signal asserted, the device is ready to execute the data transfer. At this time, the host may either execute the data transfer or select the other device. If the device has a command queue outstanding the host upper byte of the Alternate Status register contains the tag of the command associated with this service request. If the host chooses to transfer the data, the data is transferred using the existing DMA data transfer protocol. The host may break up a DMA transfer in progress by deasserting DMACK with the timing protocol described in legacy mode. Having done this, the host may select the other device. The device may break up a DMA transfer in progress by deasserting DMARQ with the timing protocol described in legacy mode. The host may then wait for DMARQ to reappear or select the other device. When the device breaks a DMA transfer by deasserting DMARQ, the device shall issue its interrupt, INTRQ, when the device is selected and DMARQ is reasserted.
- If the DMARQ signal is not asserted, the host shall read the Alternate Status register. If the Alternate Status register has DRQ and BSY both cleared and CC set, the device has completed the command. This may be an error free completion or a completion with error depending on the state of the ERR bit just as with a legacy device. If the device has a command queue outstanding, the host shall check the upper byte of the Alternate Status register to determine which command this is the completion status for.

#### 4.6.2 DMA Data Transfers in Overlap/CSsel Mode

When the data transfer can be accomplished, the device shall assert DMARQ and either INTRQ or INTRQ1 as appropriate. If the data transfer can be accomplished immediately upon receiving the command (e.g., a write command and a write buffer is available or read command the data is available in the device buffer), DMARQ may be asserted before BSY is negated. In this case, the host may chose to execute the data transfer immediately or select the other device.

When the device has completed the requested data transfer, the device shall clear DMARQ, assert ERR if applicable, and assert its interrupt, either INTRQ or INTRQ1.

When the host receives an interrupt from a device with a DMA data transfer command outstanding, it shall select the interrupting device using the protocol described above. Note that the host explicitly knows which device asserted the interrupt. The host shall then read the Status register.

- If the device has the DMARQ signal asserted, the device is ready to execute the data transfer. At this time, the host may either execute the data transfer or select the other device. If the device has a command queue outstanding the host upper byte of the Alternate Status register contains the tag of the command associated with this service request. If the host chooses to transfer the data, the data is transferred using the existing DMA data transfer protocol. The host may break up a DMA transfer in progress by deasserting DMACK with the timing protocol described in legacy mode. Having done this, the host may select the other device. The device may break up a DMA transfer in progress by deasserting DMARQ with the timing protocol described in legacy mode. The host may then wait for DMARQ to reappear or select the other device. When the device breaks a DMA transfer by deasserting DMARQ, the device shall issue its interrupt, INTRQ or INTRQ1, when the device is selected and DMARQ is reasserted.
- If the DMARQ signal is not asserted, the host shall read the Alternate Status register. If the Alternate Status register has DRQ and BSY both cleared and CC set, the device has completed the command. This may be an error free completion or a completion with error depending on the state of the ERR bit just as with a legacy device. If the device has a command queue outstanding, the host shall check the upper byte of the Alternate Status register to determine which command this is the completion status for.

### 5 ATA Standard Modifications

This clause describes the specific modifications to the existing ATA standard to incorporate Command overlap and command queuing. Added text is shown in *italics*. Deleted text is shown with crossouts,. These modifications are presented in the order that they appear in the existing standard with clause numbers appearing in X3T10/2008D revision 0.

Clause 3.1 Definitions and Abbreviations - add:

Command overlap - The ability to issue a command to the second device while the first device is in the process of executing a command.

Command queuing - The ability to issue subsequent commands to a device while previous commands have yet to complete.

Command Tag - An identifier associated with a command that allows the host to determine which of a set of queued commands is being executed.

#### Clause 4.5.1 ATA Driver Types and Required Pull-ups

Table 6

101010 0					
Signal	Source	Driver Type(1)	Pull-up at Host (2)	Pull-up at each Device (2)	Notes
IOCS16- :INTRQ1	Device	OC	1,0 kΩ		

#### Clause 5.1 Signal Summary

Table 7 Interface S	Signal Names and	Pin Assignments
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Description	Source	Pin	Acronym
16 Bit I/O or Interrupt Request 1	Device	32	IOCS16-
			:INTRQ1

Table 8 Interface signals - Alphabetical Listing

Signal	Pin
INTRQ1	32

Clause 5.2.10 INTRQ (Device interrupt) - add:

When in Overlap/CSsel mode, Device 0 shall assert INTRQ when the device has an interrupt pending and nIEN is cleared regardless of whether or not it is selected. When in overlap/DEVsel mode a device shall drive INTRQ only when selected.

Clause 5.2.11 IOCS16- (Device 16-bit I/O)

Becomes: Clause 5.2.11 IOCS16-: INTRQ1 (Device 16-bit I/O or Interrupt request 1)

Add:

When a device is in Overlap/CSsel mode, this signal is Interrupt Request 1, INTRQ1. Functionality of this signal is exactly the same as for INTRQ except that in Overlap/CSsel Mode it shall be asserted by Device 1 when Device 1 has an interrupt pending and nIEN is cleared regardless of whether Device 1 is selected or not.

Clause 6.1 Device Addressing Considerations - add:

A device may be placed in Overlap/DEVsel mode if it shares the bus with a device incapable of supporting overlap. In this case, device select is accomplished using the DEV bit as described above. In this mode, all register accesses except Device/Head register accesses are ignored when the device is not selected.

If both devices on the bus support overlap mode, both will be placed in Overlap/CSsel mode. In this mode, the DEV bit is ignored and the CS signals are used to select the devices. In this mode all register accesses are ignored when the device is not selected. Table 9a describes selection addresses when in this mode.

When in Overlap/DEVsel or Overlap/CSsel mode, all register accesses become 16-bit accesses. The content of the upper byte for Data, Command, Status, and Alternate Status accesses are defined. The upper byte of all other register accesses is reserved and shall be written as zeros and ignored on read.

Table 9a - Overlap/CSsel mode addressing

[	Addresses				Fun	octions
CS0-	CS1-	DA2	DA1	DA0	Read (DIOR-)	Write (DIOW-)
					Device 0 Contr	ol Block registers
Ν	Ν	0	х	x	Data bus high imped	Not Used
Ν	Ν	1	0	х	Data bus high imped	Not Used
Ν	Ν	1	1	0	Dev 0 Alternate Status	Dev 0 Device Control
Ν	Ν	1	1	1	Data bus high imped	Not Used
					Device 1 Contr	ol Block registers
Ν	Α	0	X	X	Data bus high imped	Not Used
Ν	Α	1	0	X	Data bus high imped	Not Used
Ν	Α	1	1	0	Dev 1 Alternate Status	Dev 1 Device Control
Ν	Α	1	1	1	Data bus high imped	Not Used
					Device 0 Comm	and Block registers
Α	N	0	0	0	Dev 0 Data	Dev 0 Data
Α	N	0	0	1	Dev 0 Error	Dev 0 Features
A	N	0	1	0	Dev 0 Sector Count	Dev 0 Sector Count
Α	Ν	0	1	1	Dev 0 Sector Number	Dev 0 Sector Number
					LBA bits 7-0 (2)	LBA bits 7-0 (2)
Α	Ν	1	0	0	Dev 0 Cylinder Low	Dev 0 Cylinder Low
					LBA bits 15-8 (2)	LBA bits 15-8 (2)
Α	Ν	1	0	1	Dev 0 Cylinder High	Dev 0 Cylinder High
					LBA bits 23-16 (2)	LBA bits 23-16 (2)
Α	Ν	1	1	0	Dev 0 Device/Head	Dev 0 Device/Head
					LBA bits 27-24 (2)	LBA bits 27-24 (2)
A	N	1	1	1	Dev 0 Status	Dev 0 Command
		-				and Block registers
A	A	0	0	0	Dev 1 Data	Dev 1 Data
Α	Α	0	0	1	Dev 1 Error	Dev 1 Features
Α	Α	0	1	0	Dev 1 Sector Count	Dev 1 Sector Count
Α	А	0	1	1	Dev 1 Sector Number	Dev 1 Sector Number
					LBA bits 7-0 (2)	LBA bits 7-0 (2)
A	А	1	0	0	Dev 1 Cylinder Low	Dev 1 Cylinder Low
	Δ	-	0		LBA bits 15-8 (2)	LBA bits 15-8 (2)
A	Α	1	0	1	Dev 1 Cylinder High	Dev 1 Cylinder High
	Δ	4	_		LBA bits 23-16 (2) LBA bits 23-16 (2	
A	А	1	1	0	Dev 1 Device/Head	Dev 1 Device/Head
	Δ	1	1	1	LBA bits 27-24 (2)	LBA bits 27-24 (2)
Α	Α	1	1	1	Dev 1 Status	Dev 1 Command

Clause 6.2.1 - Alternate Status register - add:

#### FIELD/BIT DESCRIPTION - add:

-	Overla	o Mode						
Γ	15	14	13	12	11	10	9	8
	r	r	r	r	Tag (3:0)			

- Bits 15:12- reserved
- Bits 11:8 Queue tag

Clause 6.2.2 Command register - add:

FUNCTIONAL DESCRIPTION - add:

When in overlapped mode, the host shall set the fact that a data transfer command shall execute in overlapped mode for each transfer command. If the device supports command queuing, the queue tag for the command shall also be provided.

FIELD/BIT DESCRIPTION - add:

Overlap Mode								
15	14	13	12	11	10	9	8	
OVL	r	r	r	Tag (3:0)				

Bits 15 - OVL when set indicates the command shall be executed in overlapped mode.

Bits 14-12 - reserved

Bits 11-8 - Queue tag.

Clause 6.2.7 Device/Head register - add:

FUNCTIONAL DESCRIPTION - add:

When in Overlap/CSsel Mode the DEV bit is not used for device selection and is replaced by CS signal device selection.

Clause 6.2.12 Status register - add:

FIELD/BIT DESCRIPTION - add:

- BSY (Busy) - add:

When a command is accepted and the device is in overlapped mode, BSY shall be set as described above, the device shall save the command and applicable parameters contained in command block registers, then clear BSY. This allows the host to select the other device if desired. If the device supports command queuing, another command may be issued to the device as soon as BSY has been cleared.

15	14	13	12	11	10	9	8
CC	r	r	r		TAG	(3:0)	

- CC (Command Complete) When in overlapped mode, this bit is Command Complete (CC). It is set upon completion of a command when the status for that command is present in the Status and Error registers. Upon the completion of a read from this register, the CC bit is cleared.

- TAG (3:0) When in overlapped mode with queued commands, the tag field indicates the command for which an interrupt was issued or status is being presented.

Add clause:

7.X Overlapped/Command Queuing Mode

7.X.1 Overlapped configurations

Two configurations are supported by overlapped mode.

7.X.1.1 Mixed Configurations

The mixed configuration allows one device on the bus to behave as a legacy device while the other device is operating in overlapped/queuing mode as shown in Figure X1. This allows a host that is capable of supporting overlap/queuing to make use of the functionality even when a legacy device incapable of the functionality is present. Figure X1 shows how commands for the two devices may be interleaved when Device 0 is the Legacy Device and Device 1 is the Overlapped Device. The overlapped device may in fact be configured as either Device 0 or Device 1 in this configuration.

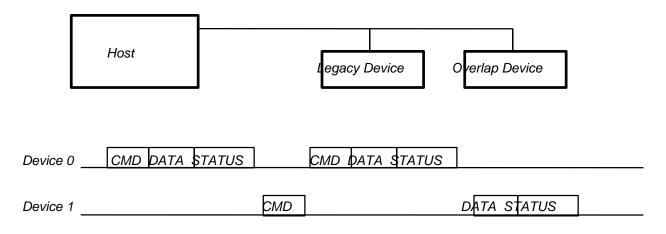
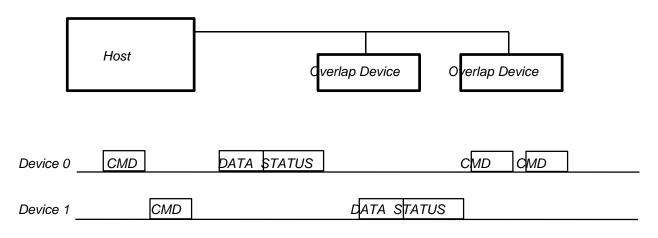


Figure X1- Mixed Configuration

#### 7.X.1.2 Overlapped Configuration

The overlapped configuration can occur when the host and both devices are capable of overlapped functionality as shown in Figure X2. Overlapped mode is designed to provide minimum overhead and maximum performance with this configuration. As shown by the first command to each device, the issuing of a command to a second device can be placed between the issuing of a command to the first device and the transfer of the first device data. If the device supports queuing as well as overlap, a subsequent commands may be issued to a device before a first command completes as shown by the second and third commands to device 0. In addition, if the data transfer is made in DMA mode, the data transfer may be completed in multiple data transfers instead of a single transfer as shown.





#### 7.X.2 Overlapped Register Ownership

When a command is issued to a device in overlapped mode, BSY is asserted. If the command is a non-data transfer command, BSY remains asserted until the command completes but if both devices support overlap, the host may select the other device as soon as the command has been written. If the command is a data transfer command, the device sets BSY, inhibits writing of its command block registers, saves the contents of the applicable command block registers, and then clears BSY. If both devices support overlap, the host may select the other may select the other device as soon as the command block registers, and then clears BSY. If both devices support overlap, the host may select the other device as soon as the command has been written. If the device supports queuing, the host may issue a second command as soon as BSY is cleared.

If the configuration is a Mixed Configuration, the host must obey the rules that each device expects. That is, if a command is issued to the legacy device, that legacy device own all registers until that command completes. The host may not access the other device. If the host issues a command to the overlapped device, the host may select the legacy device and issue it a command as soon as BSY has been cleared by the overlapped device.

#### 7.X.3 Device Selection

In a mixed configuration, a device capable of command overlap/queuing is selected just as in legacy mode. Since this device will clear its BSY bit as soon as the command parameters have been saved on a data transfer command, a host may then select the legacy device and execute a command while the overlap device is working on its data transfer command.

In an overlapped configuration where both devices are in Overlap/CSsel mode, selection is accomplished with the CS signals.

In the overlapped configuration, since both devices lockout writes to their command block registers when BSY is set and only accept writes when they are selected, a host may change the device selection at any time it is not actively transferring data or accessing a register.

#### 7.X.4 Interrupt Reporting

When placed in Overlap/CSsel mode, a device implementing this function will use either the INTRQ line, or the IOCS16-/INTRQ1 line for reporting interrupts. That is, when in Overlap/CSsel mode, Device 0 shall interrupt using INTRQ; Device 1 shall interrupt using IOCS16-/INTRQ1. These interrupts may be asserted at any time regardless of whether or not the device is currently selected. This allows the devices to notify the host that service is required regardless of current selection and allows the host to know exactly who is interrupting.

When in Overlap/DEVsel Mode, the device shall use INTRQ for interrupts as in legacy mode and shall assert INTRQ only when selected.

#### 7.X.5 Command Queue Tags

The Identify Device info returned by a device capable of overlap/queuing operation shall contain a four bit queue depth field. If this field is 0h, the device does not support queuing. If the field contains any other value, this value plus one indicates the depth of queue supported up to a maximum queue depth of sixteen. Any tag issued by the host with a tag number greater than this value shall cause the command to be aborted.

When issuing a data transfer command to a device in overlapped/queuing mode, the tag field in the upper byte of the Command register shall indicate that this is an overlapped command and provide the queue tag number for this command.

When a queued device interrupts for service for a queued command, the tag for the command requiring service shall be contained in the upper byte of the Status or Alternate Status register.

All queued commands are simple queued data transfer commands, no priority is implied.

#### 7.x.6 Host synchronization

Command overlap and command queuing make the use of an intelligent DMA engine in the host an attractive added feature to improve performance particularly with a multithreaded operating system. However, with such an intelligent DMA engine, the accesses to the devices by the DMA engine and the host device driver must be synchronized. That is, the device driver may not access the devices while the DMA engine is in the process of transferring data to/from a device, and the DMA engine may not transfer data while the host device driver is accessing registers to issue a command or check status.

The following is an example of how this synchronization may be accomplished. The DMA engine will have a register accessible by the host. The ATAREQ bit in the register will be writable by the host. When the host device driver wishes to access a device to issue a command or read status, the host will set the ATAREQ bit to one.

If the DMA engine is not currently transferring data to/from a device, it will set the ATAACK bit to one. When both the ATAREQ and ATAACK bits are one, the host device driver may access a device and the DMA engine Shall not access a device.

If the DMA engine is in the process of transferring data to/from a device when the ATAREQ bit is set, it will complete the transfer and then set the ATAACK bit to one.

When the host device driver has completed the required device accesses, it will set the ATAREQ bit to zero. The DMA engine will immediately set the ATAACK bit to zero, and the DMA engine may now access a device.

In this way, accesses by the DMA engine and the host device driver are synchronized.

#### Clause 8.10 IDENTIFY DEVICE - add:

Table 14 - Identify Device Information - add:

Word	F/V	
71	F	15 Overlapped Mode supported
		14-11 Queue depth supported
		10-0 Reserved
72-127	R	Reserved

Add clause 8.10.36 Word 71: Overlapped Mode/Command Queuing Supported

Word 71 of the parameter information of the IDENTIFY DEVICE command is defined as the Overlapped Mode/Command Queuing supported field. If bit 15 is set to one, the device supports Overlapped Mode. This mode may be set via a SET FEATURES command.

Bits 14-11 define the queue depth supported if command queuing is supported when in overlapped mode. If 0h is present in this field, the device does not support command queuing. If this field contains a value other than 0h, that value + 1 is the maximum queue depth supported by the device.

#### Clause 8.32 SET FEATURES add:

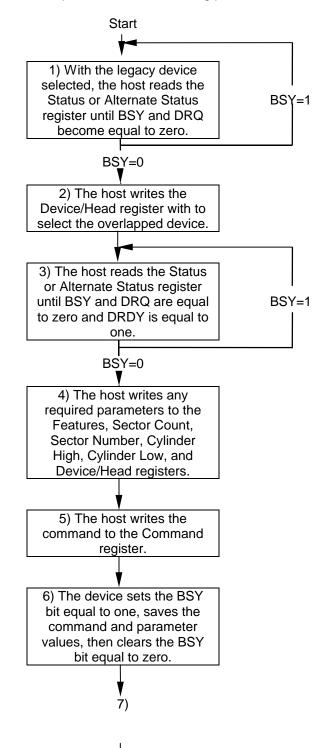
Table 17 - Set Features register Definitions add:

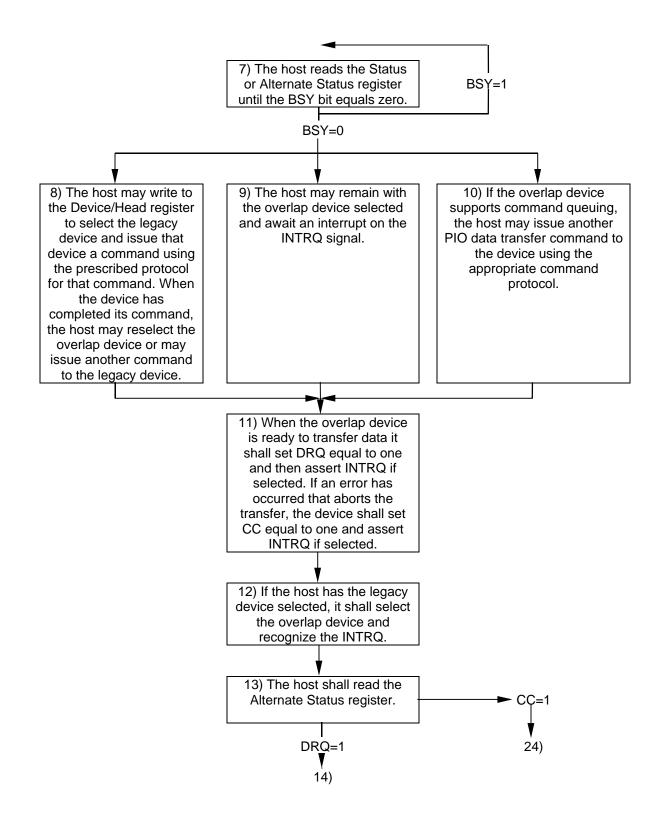
DDh	Enable Overlap/DEVsel mode	
DEh	Enable Overlap/CSsel mode	
DFh	Disable Overlap mode	

Clause 9.3 PIO data in commands - add:

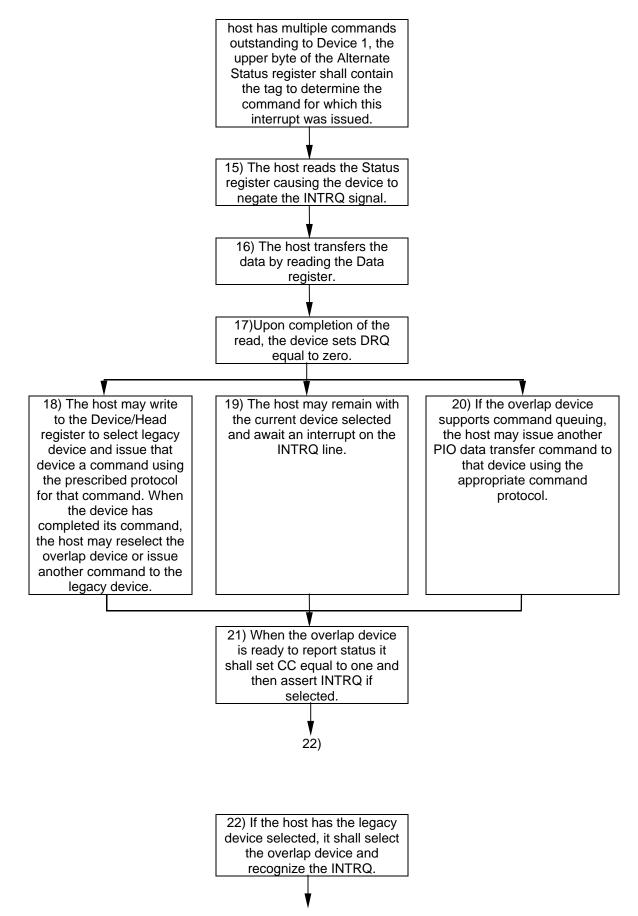
9.3.1 Overlap/DEVsel mode PIO data in commands

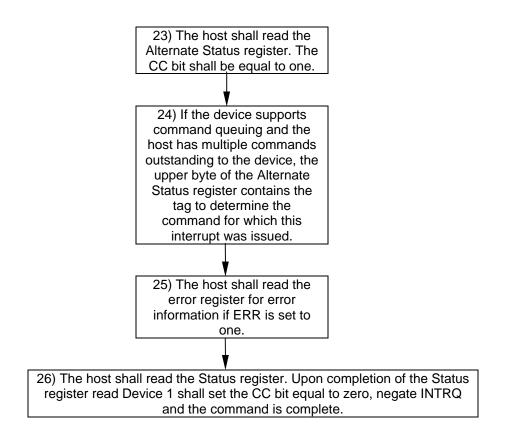
When a mixed configuration exists with one legacy device and one device that supports overlapped mode, the device that supports overlapped mode may be set into Overlap/DEVsel mode. The overlapped device then operates with the following protocol:





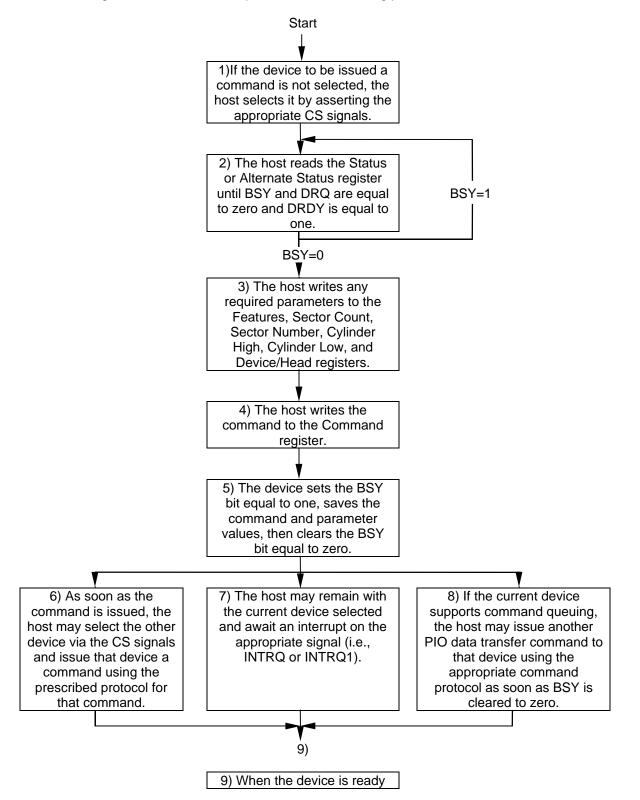
14) If the device supports
command queuing and the

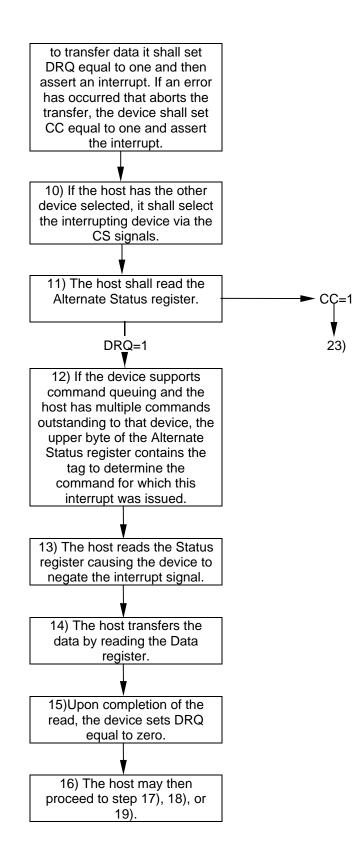


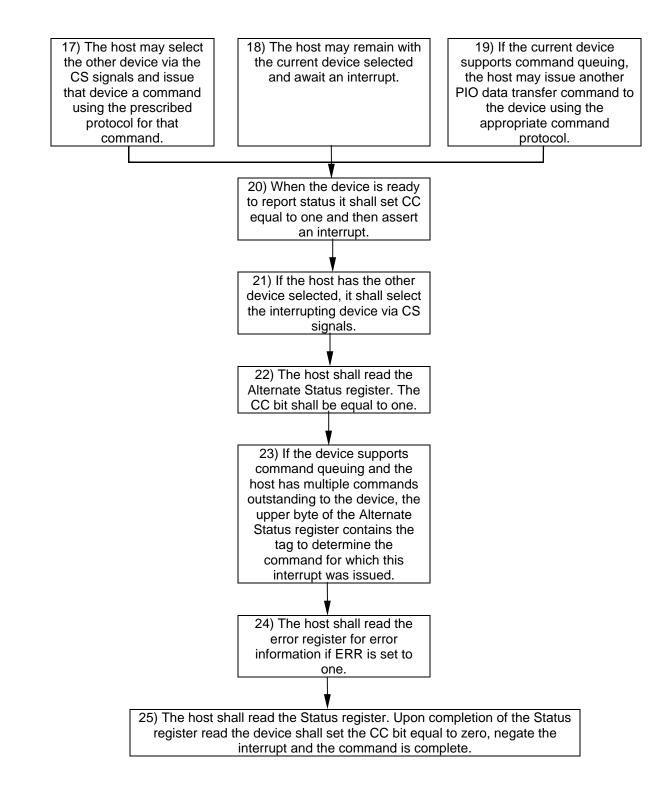


#### 9.3.1 Overlap/CSsel mode PIO data in commands

When an overlapped configuration exists with both devices that support overlapped mode, the devices are set into Overlap/CSsel mode. In this configuration, device selection is accomplished via the CS signals. The device then operate with the following protocol:



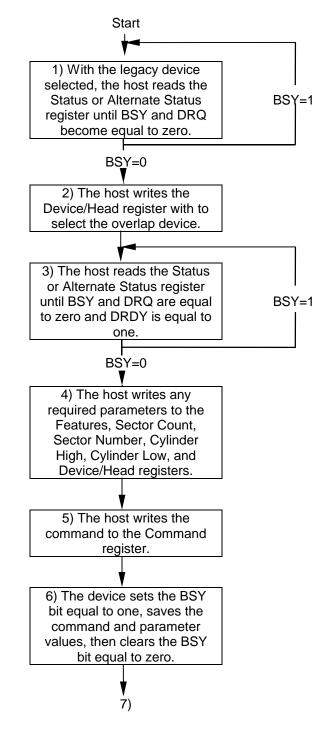


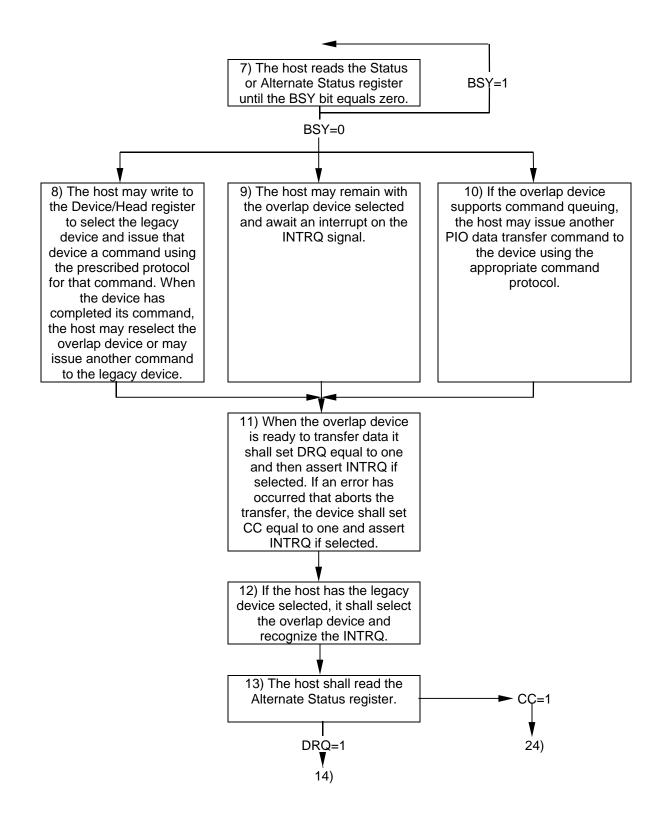


Clause 9.4 PIO data out commands - add:

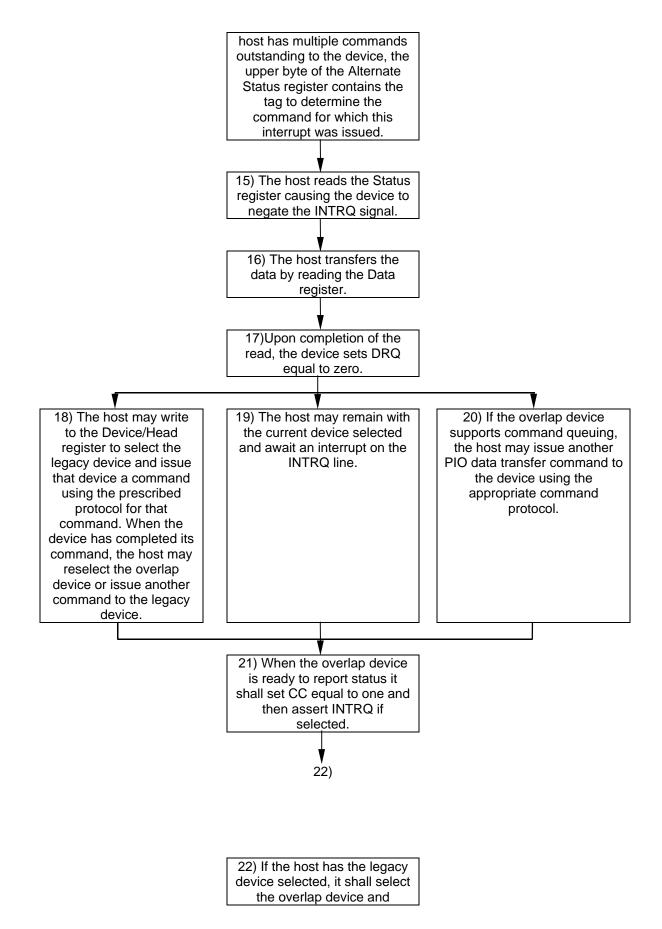
9.3.1 Overlap/DEVsel mode PIO data in commands

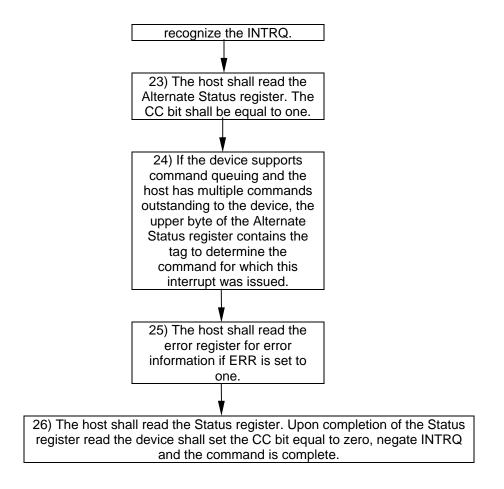
When a mixed configuration exists with one legacy device and one device that supports overlapped mode, the device that supports overlapped mode may be set into Overlap/DEVsel mode. The overlapped device then operates with the following protocol:





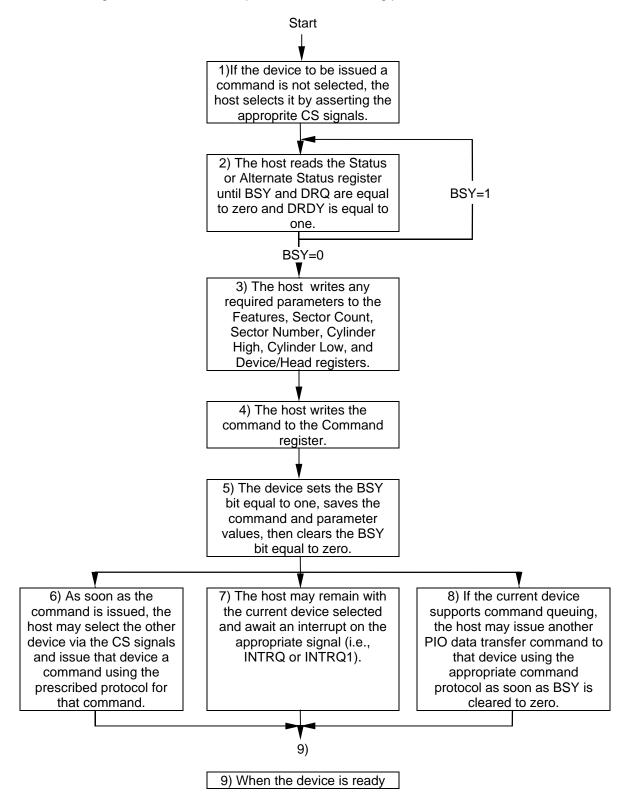
14) If the device supports
command queuing and the

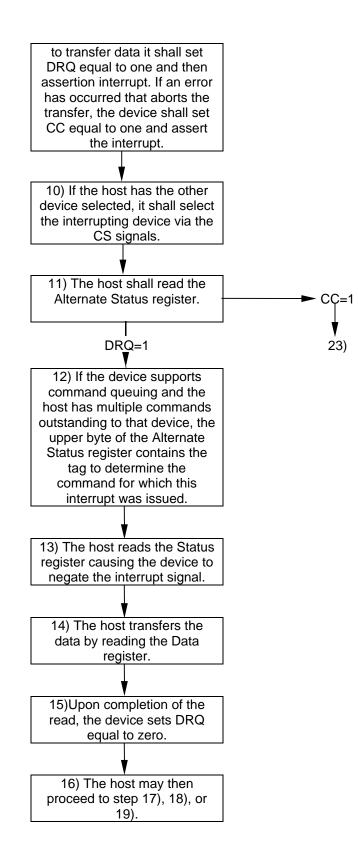


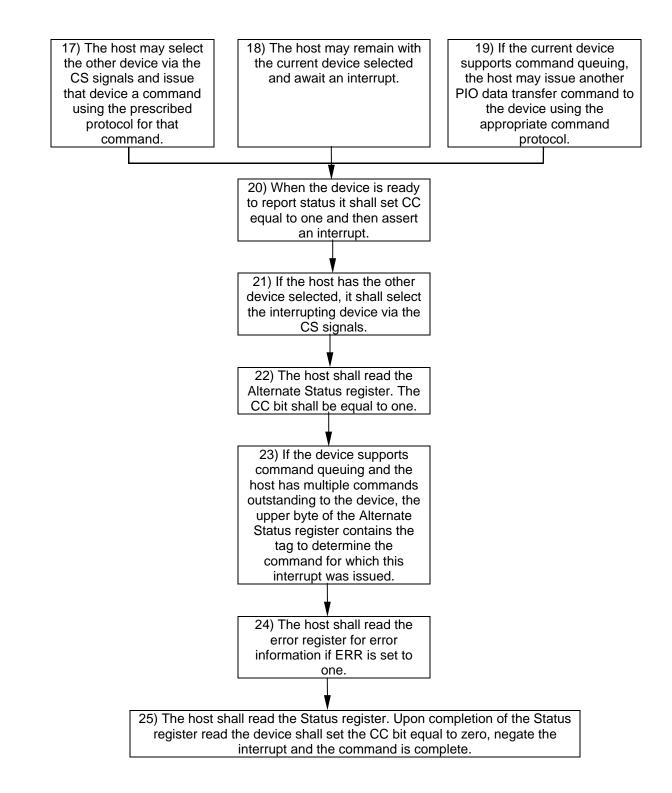


#### 9.3.1 Overlap/CSsel mode PIO data in commands

When an overlapped configuration exists with both devices that support overlapped mode, the devices are set into Overlap/CSsel mode. In this configuration, device selection is accomplished via the CS signals. The device then operate with the following protocol:



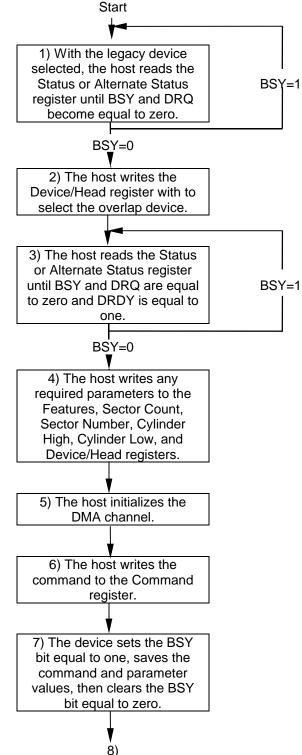


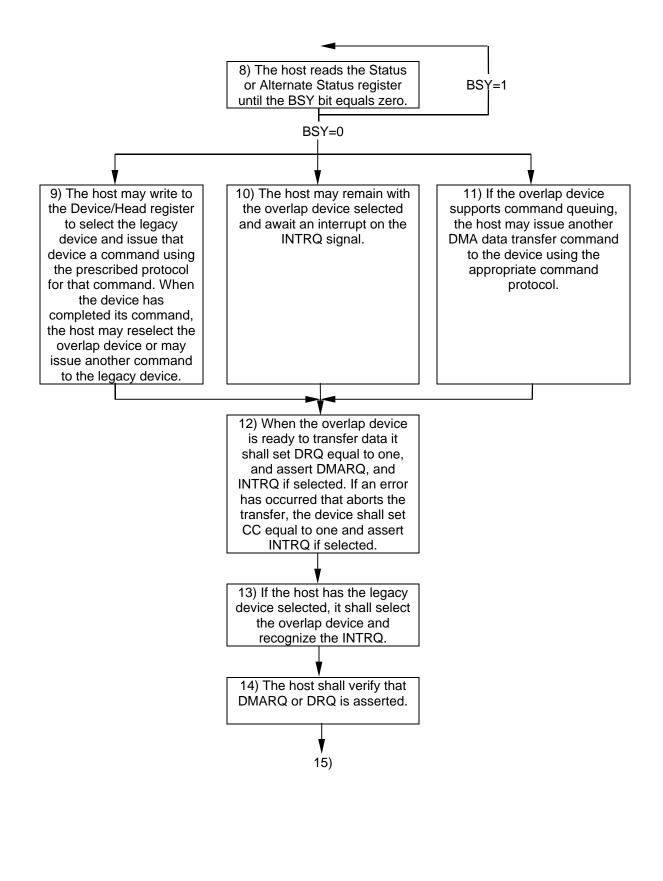


Clause 9.6 DMA data transfer commands - add:

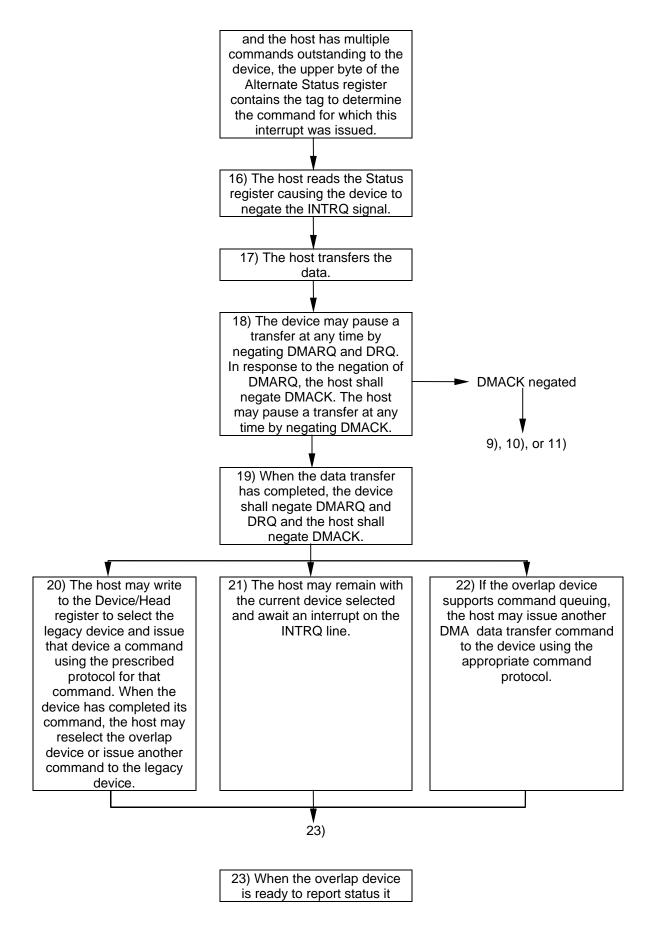
9.6.1 Overlap/DEVsel mode DMA data transfer commands

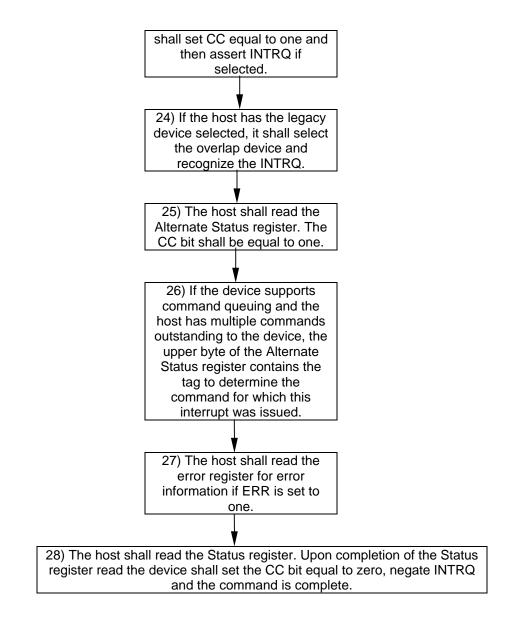
When a mixed configuration exists with one legacy device and one device that supports overlapped mode, the device that supports overlapped mode may be set into Overlap/DEVsel mode. The overlapped device then operates with the following protocol:





15) If the overlap device	
supports command queuing	





9.6.1 Overlap/CSsel mode DMA data transfer commands

When an overlapped configuration exists with both devices that support overlapped mode, the devices are set into Overlap/CSsel mode. In this configuration, device selection is accomplished via the CS signals. The device then operate with the following protocol:

