

T10/08-320r1 SMC-3 Use of NOT READY error codes

To: T10 Technical Committee

From: Noud Snelder, BDT (noud.snelder@bdt.de)

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Subject: T10/08-320r1 SMC-3 Use of NOT READY error codes

Revision History

Revision 0 (30 July 2008): initial revision

Revision 1 (29 April 2009): added comments from March SMC-3 working group meeting

Related Documents

SMC3r11 - SCSI Media Changer Commands - 3

08-272r1 – SMC-3 New additional sense codes tracking document

Overview

The SMC3 working group is attempting to define commonly used error codes in the standard to increase level of standardization. The document 08-272 list all new SMC-3 error codes. This document describes some of these new error codes.

Suggested Changes to SMC-3

Proposed new text is shown in blue. Proposed deletions are shown in ~~red~~ ~~strikeout~~.

[Add definition:]

3.1.x ready state: A state where a logical unit is able to process a medium-access command without returning CHECK CONDITION status with the sense key set to NOT READY.

3.1.y sequential mode: A mode of the logical unit that is beyond the scope of this specification.

3.1.z robotic motion commands: Commands that may require robotic movement (e.g, EXCHANGE MEDIUM, INITIALIZE ELEMENT STATUS, INITIALIZE ELEMENT STATUS WITH RANGE, MOVE MEDIUM, OPEN CLOSE IMPORT EXPORT ELEMENT, and READ ELEMENT STATUS).

[Add paragraphs:]

5.6 Error ~~conditions~~ **reporting**

5.6.1 Not ready error conditions

This sub clause describes library states that prevent normal operation.

5.6.1.1 Sequential mode

If the logical unit is configured in sequential mode (see 3.1.y), then the device server shall terminate robotic motion commands (see 3.1.z) and may terminate other commands with CHECK CONDITION status with the sense key set to NOT READY and the additional sense code set to LOGICAL UNIT NOT READY, OPERATING IN SEQUENTIAL MODE.

5.6.1.2 Door open

If the logical unit has an access door in a state that does not allow the device server to process robotic motion commands, then the device server may terminate the command with CHECK CONDITION status with the sense key set to NOT READY and the additional sense code set to LOGICAL UNIT NOT READY, A DOOR IS OPEN.

5.6.1.3 Calibration required

If the logical unit is unable to process robotic motion commands successfully due to a missing calibration, then the device server may terminate the command with CHECK CONDITION status with the sense key set to NOT READY and the additional sense code set to LOGICAL UNIT NOT READY, CALIBRATION REQUIRED. The calibration may be performed by:

- a) an INITIALIZE ELEMENT STATUS command;
- b) a Power cycle;
- c) a Service intervention; or
- d) a Vendor specific command.

5.6.1.4 Media changer configuration required

If the logical unit is unable to process commands successfully due to missing configuration settings, then the device server may terminate the command with CHECK CONDITION status with the sense key set to NOT READY and the additional sense code set to LOGICAL UNIT NOT READY, MEDIA CHANGER CONFIGURATION REQUIRED.

5.6.1.5 Robotics disabled

If the logical unit is unable to process commands due to disabled robotics mechanism, then the device server may terminate the command with CHECK CONDITION status with the sense key set to NOT READY and the additional sense code set to LOGICAL UNIT NOT READY, ROBOTICS DISABLED.