



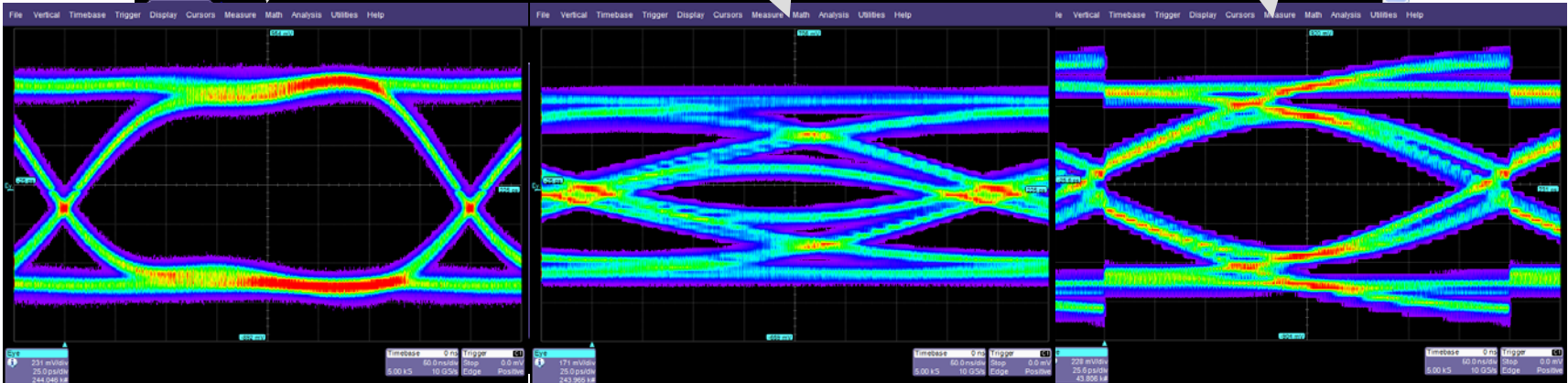
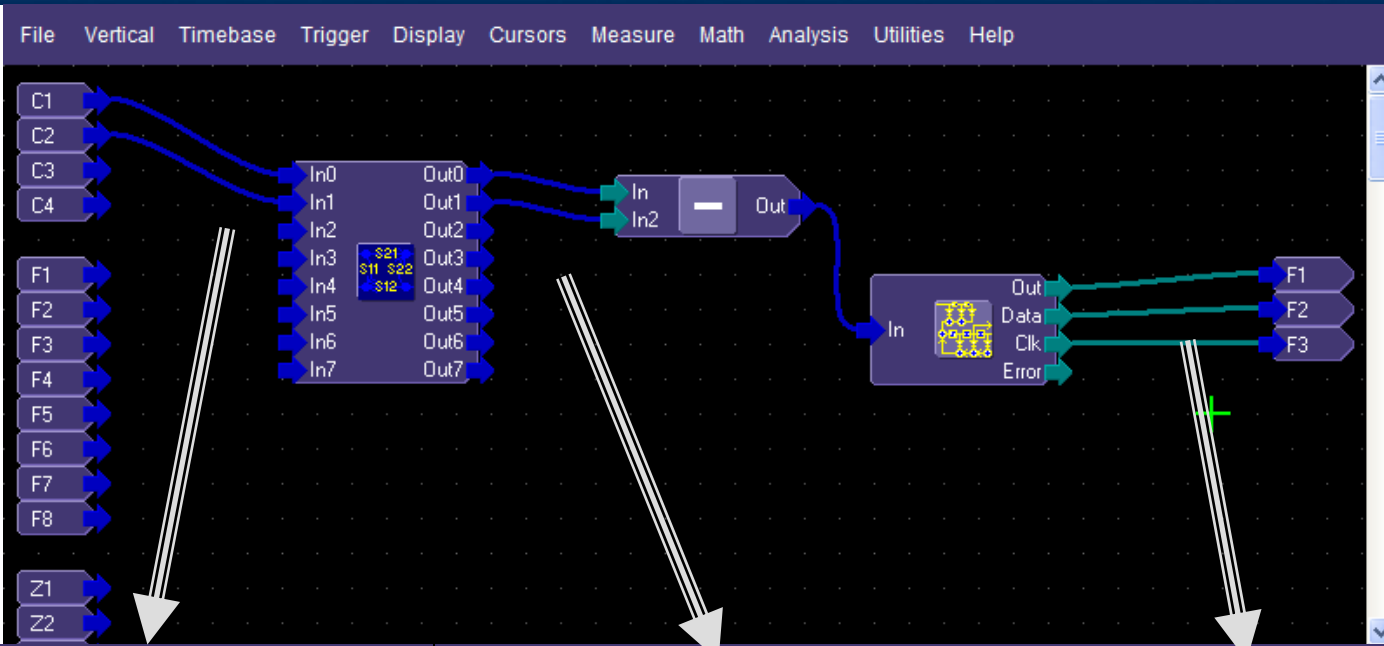
SAS-2 Virtual Probing And Equalizer Emulation

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LeCroy Corp.

The Eye Doctor Solution



Measured Signal at Transmitter
July 8, 2007

Virtually Probed Signal at Receiver
T10/07-323r0

Equalized Signal

Equalizer overview

■ Linear

– Unsampld

- Continuous-time (CTLE)
- Transversal FIR

– Sampled

- Rx FIR
- Tx FIR

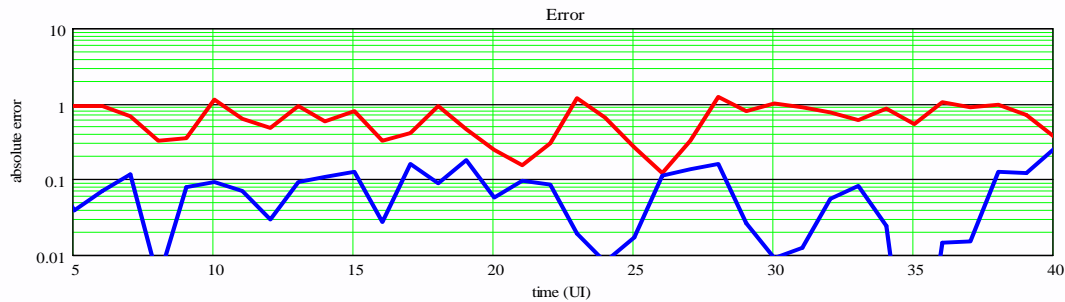
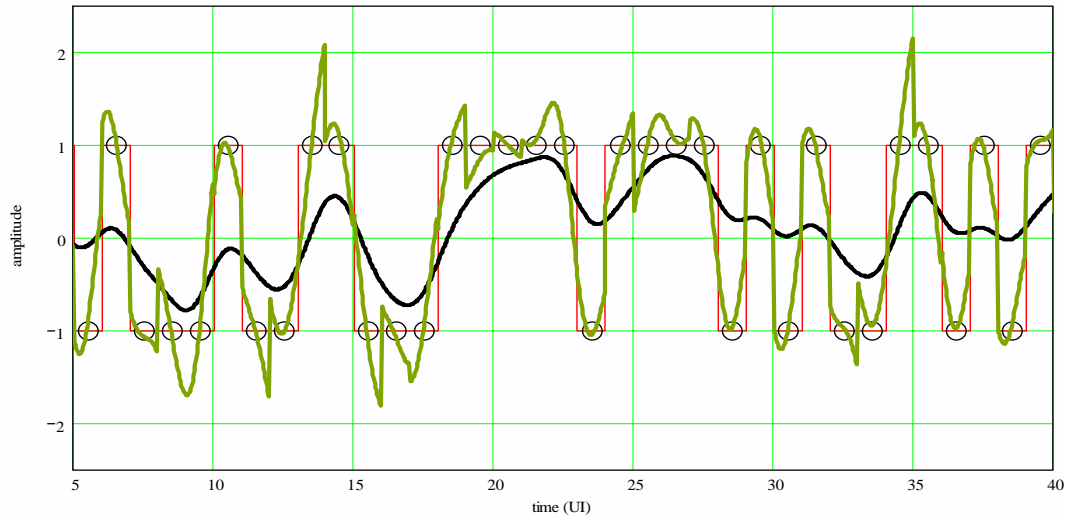
■ Non-linear

- Decision Feedback Equalization (DFE)

Most commonly used equalizers

Implemented in Eye Doctor

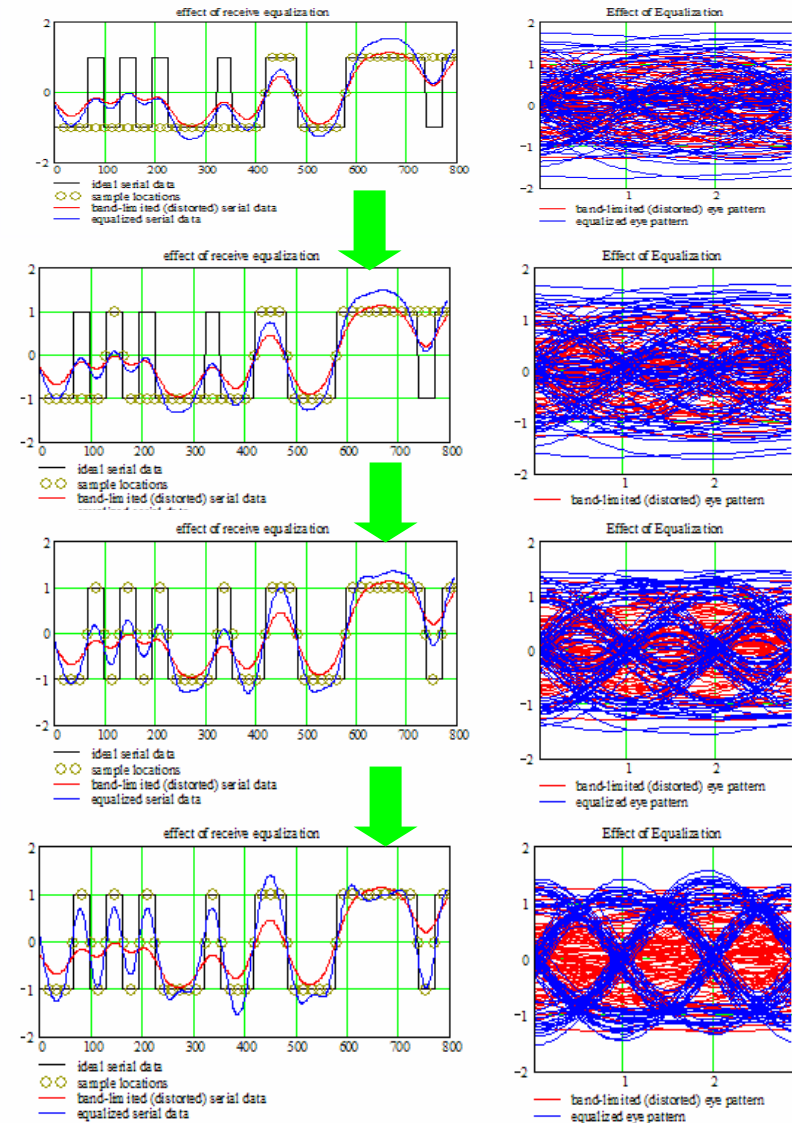
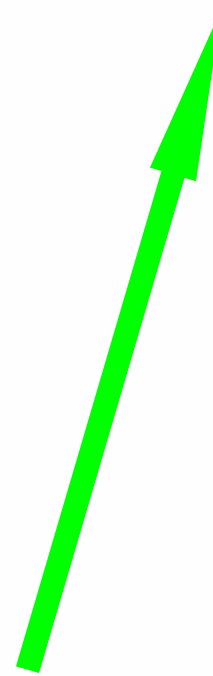
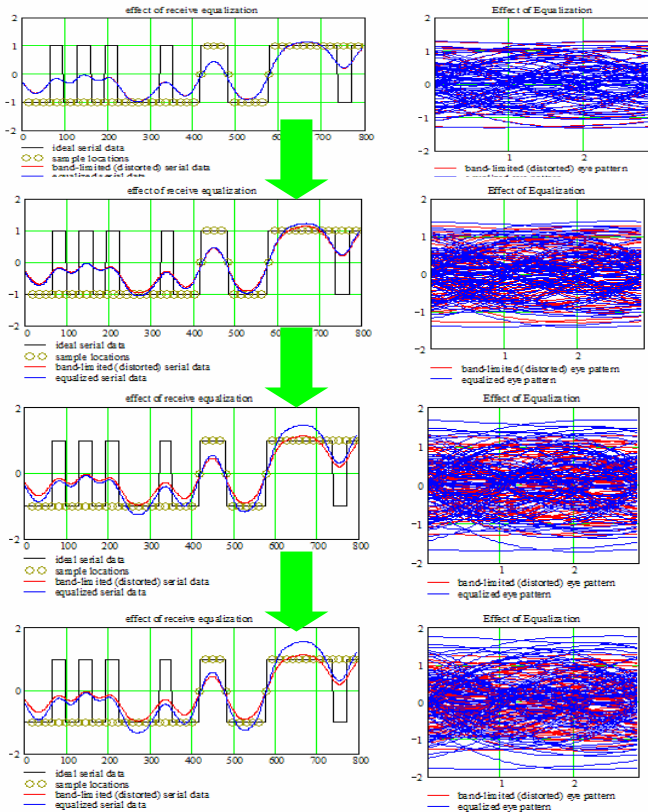
Minimum Mean-Squared Error



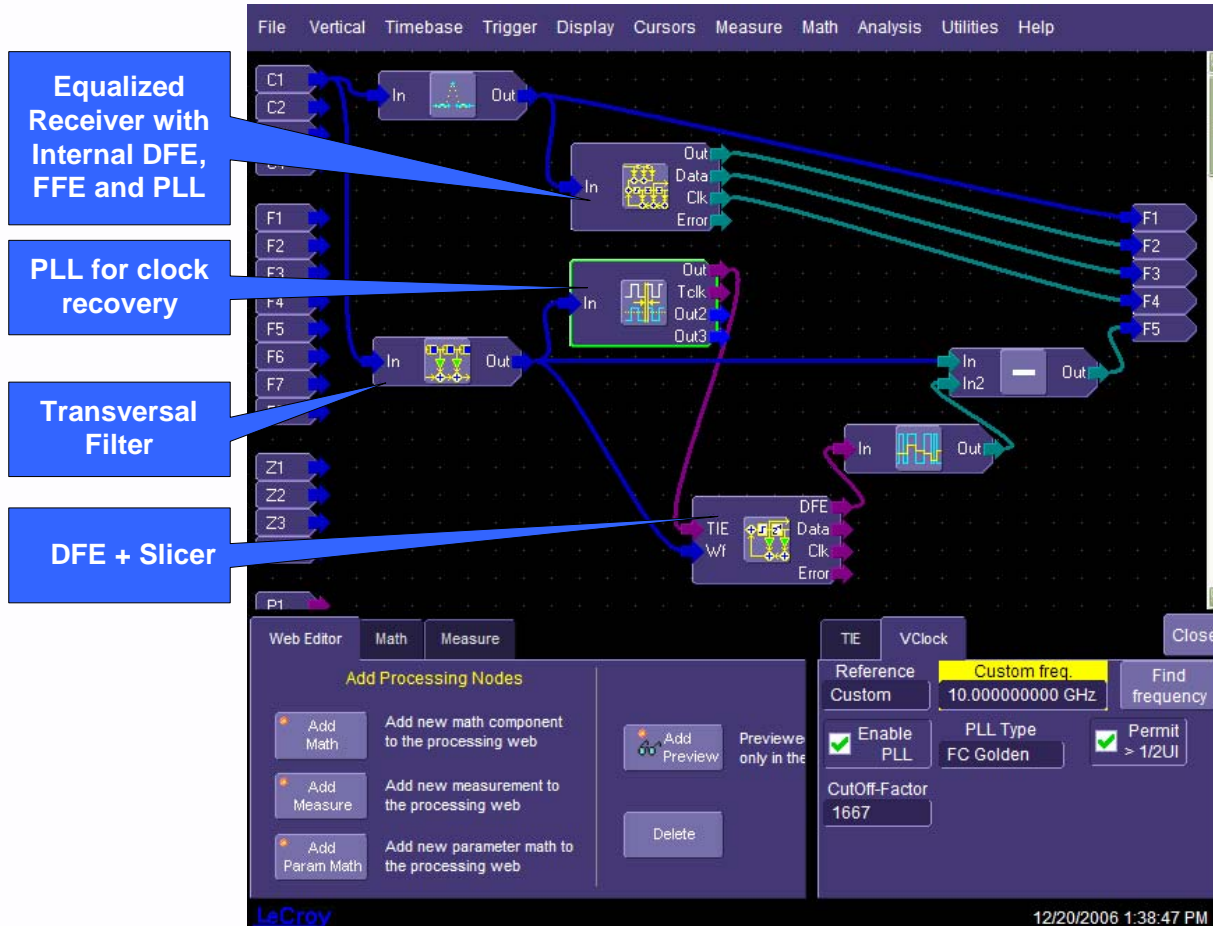
Note:
logarithmic
scale

Error signal

Decision Directed Learning (Blind Adaptation)

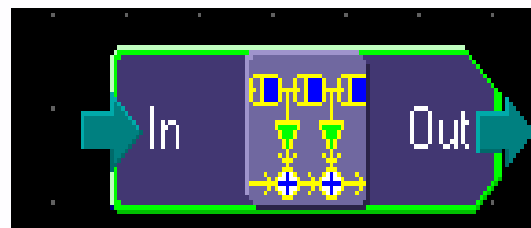
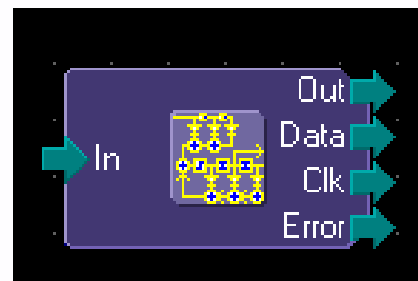


Equalizer Emulation Components



Setting Up Equalization

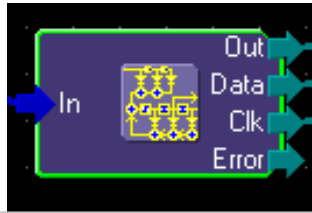
- DFE
 - Use equalized receiver
 - Set number of taps and train
- FFE
 - Use linear tapped delay line filter
 - Set number taps and train
- De-emphasis
 - Use linear tapped-delay line filter
 - Set taps to 3
 - Set bit time interval (tap delay)
 - Enter weights: -N, 1-N for 1-2N de-emphasis



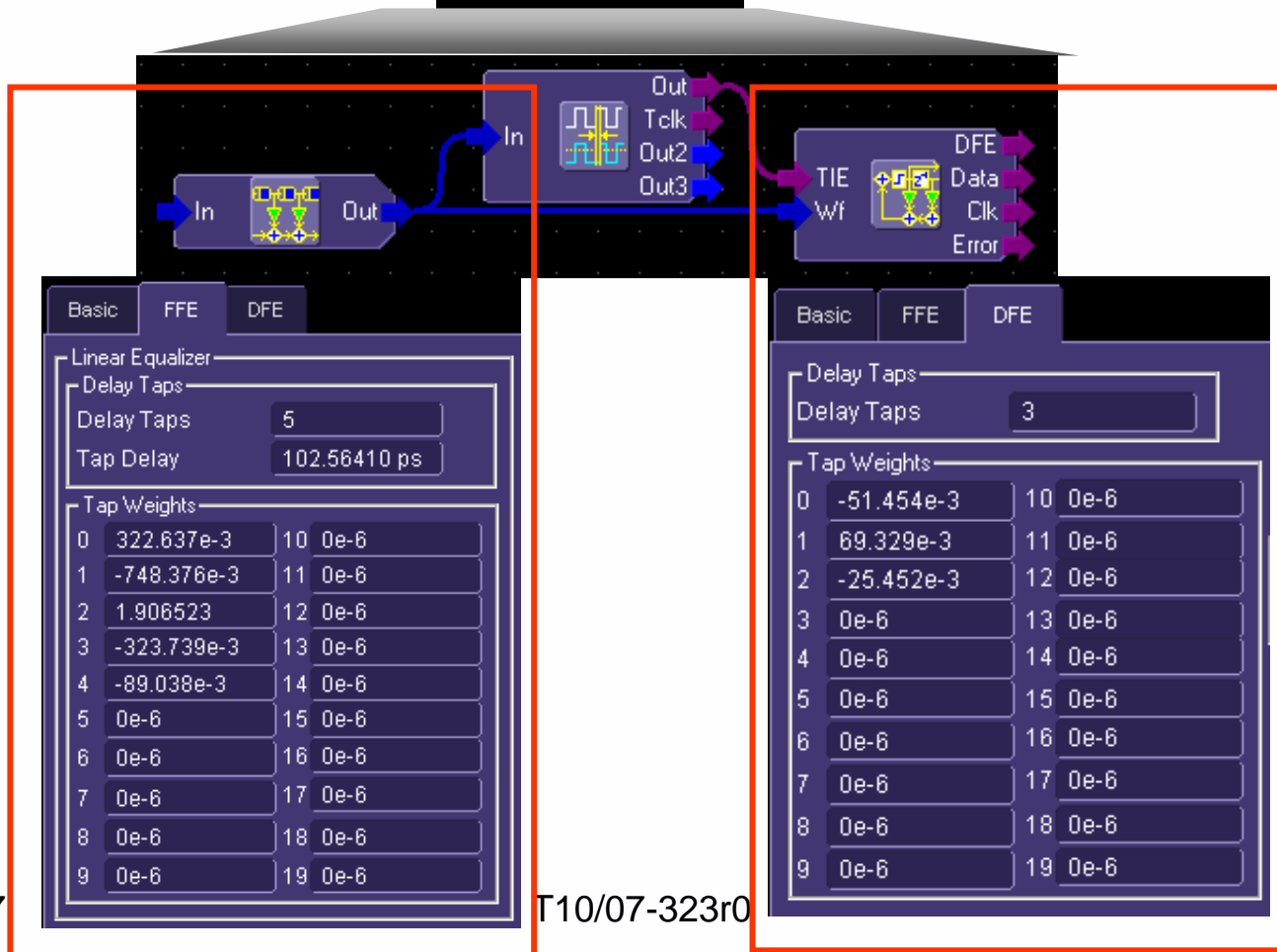
Equalizer Emulation

Configuration of the equalizer emulator

FFE (Feed Forward Equalizer)

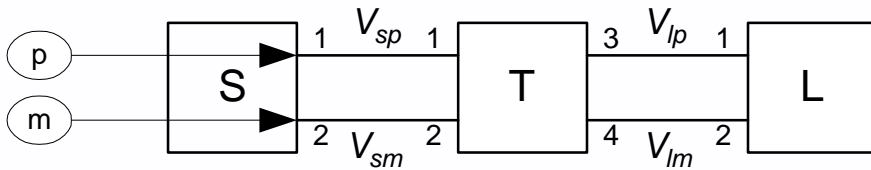


DFE (Decision Feedback Equalizer)

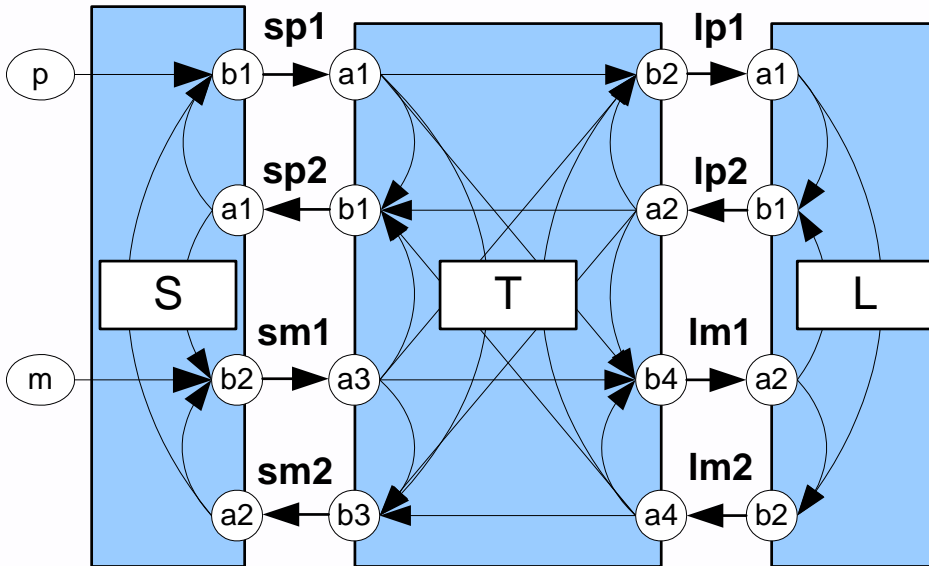


Virtual Probing Theory of Operation

Network Diagram



Signal Flow Diagram



System Description File

```
.device S 2 file "s.s2p"
.device T 4 file "t.s4p"
.device L 2 file "l.s2p"
.node vsp S 1 T 1
.node vsm S 2 T 2
.node vlp T 3 L 1
.node vlm T 4 L 2
.stim p S 1
.stim m S 2
.meas vsp
.meas vsm
.output vlp
.output vlm
```

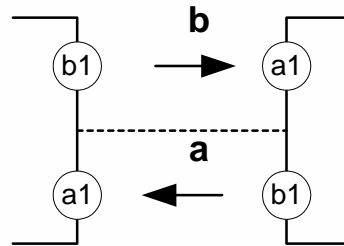
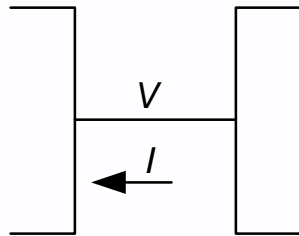
Power Wave Relationship

$$a = \frac{V + I \cdot Z_0}{2 \cdot \sqrt{Z_0}}$$

$$b = \frac{V - I \cdot Z_0}{2 \cdot \sqrt{Z_0}}$$

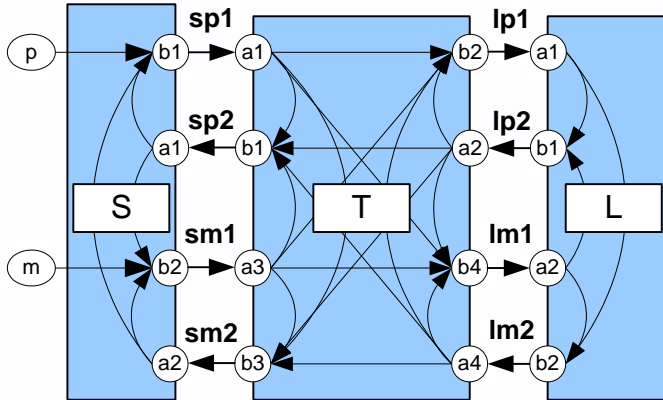
$$V = (a + b) \cdot \sqrt{Z_0}$$

$$I = (a - b) \cdot \frac{\sqrt{Z_0}}{Z_0}$$



- Voltage is voltage at node
- Current is into leftmost port
- A is incident wave on leftmost port
- B is reflected wave from leftmost port

Voltage Relationships

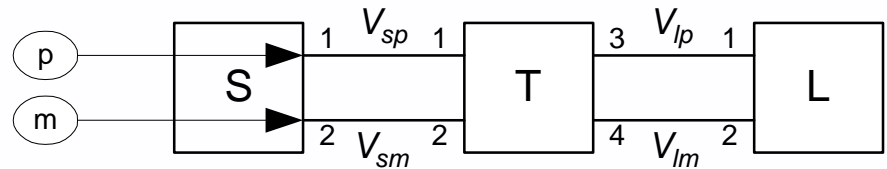


$$V_{sp} = (sp1 + sp2) \cdot \sqrt{Z0}$$

$$V_{sm} = (sm1 + sm2) \cdot \sqrt{Z0}$$

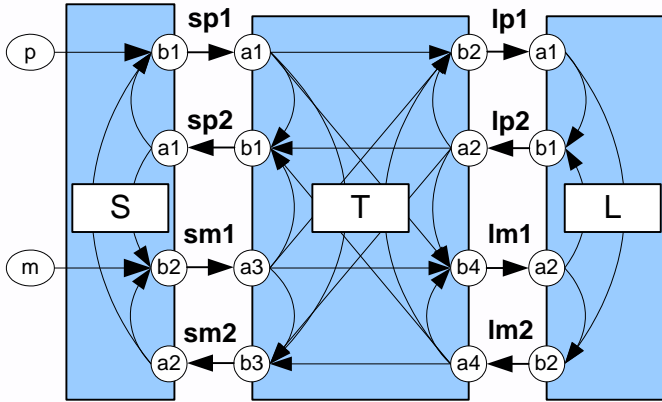
$$V_{lp} = (lp1 + lp2) \cdot \sqrt{Z0}$$

$$V_{lm} = (lm1 + lm2) \cdot \sqrt{Z0}$$



$$V = \begin{bmatrix} V_{sp} \\ V_{sm} \\ V_{lp} \\ V_{lm} \end{bmatrix} = \sqrt{Z0} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} sp_1 \\ sm_1 \\ sp_2 \\ sm_2 \\ lp_1 \\ lm_1 \\ lp_2 \\ lm_2 \end{bmatrix}$$

Systems of Equations



$$\begin{aligned}
 sp1 &= p + sS_{12} \cdot sm2 + sS_{11} \cdot sp2 \\
 sp2 &= sT_{11} \cdot sp1 + sT_{13} \cdot sm1 + sT_{12} \cdot lp2 + sT_{14} \cdot lm2 \\
 sm1 &= m + sS_{21} \cdot sp2 + sS_{22} \cdot sm2 \\
 sm2 &= sT_{33} \cdot sm1 + sT_{31} \cdot sp1 + sT_{32} \cdot lp2 + sT_{34} \cdot lm2 \\
 lp1 &= sT_{21} \cdot sp1 + sT_{23} \cdot sm1 + sT_{24} \cdot lm2 + sT_{22} \cdot lp2 \\
 lp2 &= sL_{11} \cdot lp1 + sL_{12} \cdot lm1 \\
 lm1 &= sT_{42} \cdot lp2 + sT_{41} \cdot sp1 + sT_{43} \cdot sm1 + sT_{44} \cdot lm2 \\
 lm2 &= sL_{22} \cdot lm1 + sL_{21} \cdot lp1
 \end{aligned}$$

$$\begin{bmatrix}
 1 & 0 & -sS_{11} & -sS_{12} & 0 & 0 & 0 & 0 \\
 0 & 1 & -sS_{21} & -sS_{22} & 0 & 0 & 0 & 0 \\
 -sT_{11} & -sT_{12} & 1 & 0 & 0 & 0 & -sT_{13} & -sT_{14} \\
 -sT_{21} & -sT_{22} & 0 & 1 & 0 & 0 & -sT_{23} & -sT_{24} \\
 -sT_{31} & -sT_{32} & 0 & 0 & 1 & 0 & -sT_{33} & -sT_{34} \\
 -sT_{41} & -sT_{42} & 0 & 0 & 0 & 1 & -sT_{43} & -sT_{44} \\
 0 & 0 & 0 & 0 & -sL_{11} & -sL_{12} & 1 & 0 \\
 0 & 0 & 0 & 0 & -sL_{21} & -sL_{22} & 0 & 1
 \end{bmatrix} \cdot \begin{bmatrix} sp_1 \\ sm_1 \\ sp_2 \\ sm_2 \\ lp_1 \\ lm_1 \\ lp_2 \\ lm_2 \end{bmatrix} = \begin{bmatrix} p \\ m \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

The Simulator Solution

$$\begin{bmatrix} 1 & 0 & -sS_{11} & -sS_{12} & 0 & 0 & 0 & 0 \\ 0 & 1 & -sS_{21} & -sS_{22} & 0 & 0 & 0 & 0 \\ -sT_{11} & -sT_{12} & 1 & 0 & 0 & 0 & -sT_{13} & -sT_{14} \\ -sT_{21} & -sT_{22} & 0 & 1 & 0 & 0 & -sT_{23} & -sT_{24} \\ -sT_{31} & -sT_{32} & 0 & 0 & 1 & 0 & -sT_{33} & -sT_{34} \\ -sT_{41} & -sT_{42} & 0 & 0 & 0 & 1 & -sT_{43} & -sT_{44} \\ 0 & 0 & 0 & 0 & -sL_{11} & -sL_{12} & 1 & 0 \\ 0 & 0 & 0 & 0 & -sL_{21} & -sL_{22} & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} sp_1 \\ sm_1 \\ sp_2 \\ sm_2 \\ lp_1 \\ lm_1 \\ lp_2 \\ lm_2 \end{bmatrix} = \begin{bmatrix} p \\ m \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$Si = \begin{bmatrix} 1 & 0 & -sS_{11} & -sS_{12} & 0 & 0 & 0 & 0 \\ 0 & 1 & -sS_{21} & -sS_{22} & 0 & 0 & 0 & 0 \\ -sT_{11} & -sT_{12} & 1 & 0 & 0 & 0 & -sT_{13} & -sT_{14} \\ -sT_{21} & -sT_{22} & 0 & 1 & 0 & 0 & -sT_{23} & -sT_{24} \\ -sT_{31} & -sT_{32} & 0 & 0 & 1 & 0 & -sT_{33} & -sT_{34} \\ -sT_{41} & -sT_{42} & 0 & 0 & 0 & 1 & -sT_{43} & -sT_{44} \\ 0 & 0 & 0 & 0 & -sL_{11} & -sL_{12} & 1 & 0 \\ 0 & 0 & 0 & 0 & -sL_{21} & -sL_{22} & 0 & 1 \end{bmatrix}^{-1}$$

$$\begin{bmatrix} sp_1 \\ sm_1 \\ sp_2 \\ sm_2 \\ lp_1 \\ lm_1 \\ lp_2 \\ lm_2 \end{bmatrix} = Si \cdot \begin{bmatrix} p \\ m \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} sp_1 \\ sm_1 \\ sp_2 \\ sm_2 \\ lp_1 \\ lm_1 \\ lp_2 \\ lm_2 \end{bmatrix} = \begin{bmatrix} Si_{0,0} & Si_{0,1} \\ Si_{1,0} & Si_{1,1} \\ Si_{2,0} & Si_{2,1} \\ Si_{3,0} & Si_{3,1} \\ Si_{4,0} & Si_{4,1} \\ Si_{5,0} & Si_{5,1} \\ Si_{6,0} & Si_{6,1} \\ Si_{7,0} & Si_{7,1} \end{bmatrix} \cdot \begin{bmatrix} p \\ m \end{bmatrix}$$

$$\begin{bmatrix} V_{sp} \\ V_{sm} \\ V_{lp} \\ V_{lm} \end{bmatrix} = \sqrt{Z0} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} Si_{0,0} & Si_{0,1} \\ Si_{1,0} & Si_{1,1} \\ Si_{2,0} & Si_{2,1} \\ Si_{3,0} & Si_{3,1} \\ Si_{4,0} & Si_{4,1} \\ Si_{5,0} & Si_{5,1} \\ Si_{6,0} & Si_{6,1} \\ Si_{7,0} & Si_{7,1} \end{bmatrix} \cdot \begin{bmatrix} p \\ m \end{bmatrix}$$

- Simulators need to solve for voltages with respect to stimuli.
- Virtual Probing is not a simulator.

The Transfer Function Solution

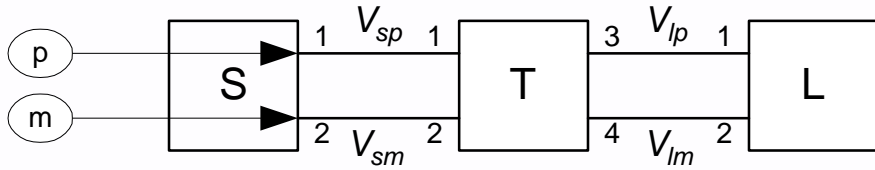
$$\begin{bmatrix} V_{sp} \\ V_{sm} \\ V_{lp} \\ V_{lm} \end{bmatrix} = \sqrt{Z_0} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{0,0}} & S_{i_{0,1}} \\ S_{i_{1,0}} & S_{i_{1,1}} \\ S_{i_{2,0}} & S_{i_{2,1}} \\ S_{i_{3,0}} & S_{i_{3,1}} \\ S_{i_{4,0}} & S_{i_{4,1}} \\ S_{i_{5,0}} & S_{i_{5,1}} \\ S_{i_{6,0}} & S_{i_{6,1}} \\ S_{i_{7,0}} & S_{i_{7,1}} \end{bmatrix} \cdot \begin{bmatrix} p \\ m \end{bmatrix}$$

$$\begin{bmatrix} V_{sp} \\ V_{sm} \end{bmatrix} = \sqrt{Z_0} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{0,0}} & S_{i_{0,1}} \\ S_{i_{1,0}} & S_{i_{1,1}} \\ S_{i_{2,0}} & S_{i_{2,1}} \\ S_{i_{3,0}} & S_{i_{3,1}} \end{bmatrix} \cdot \begin{bmatrix} p \\ m \end{bmatrix} \quad \begin{bmatrix} V_{lp} \\ V_{lm} \end{bmatrix} = \sqrt{Z_0} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{4,0}} & S_{i_{4,1}} \\ S_{i_{5,0}} & S_{i_{5,1}} \\ S_{i_{6,0}} & S_{i_{6,1}} \\ S_{i_{7,0}} & S_{i_{7,1}} \end{bmatrix} \cdot \begin{bmatrix} p \\ m \end{bmatrix}$$

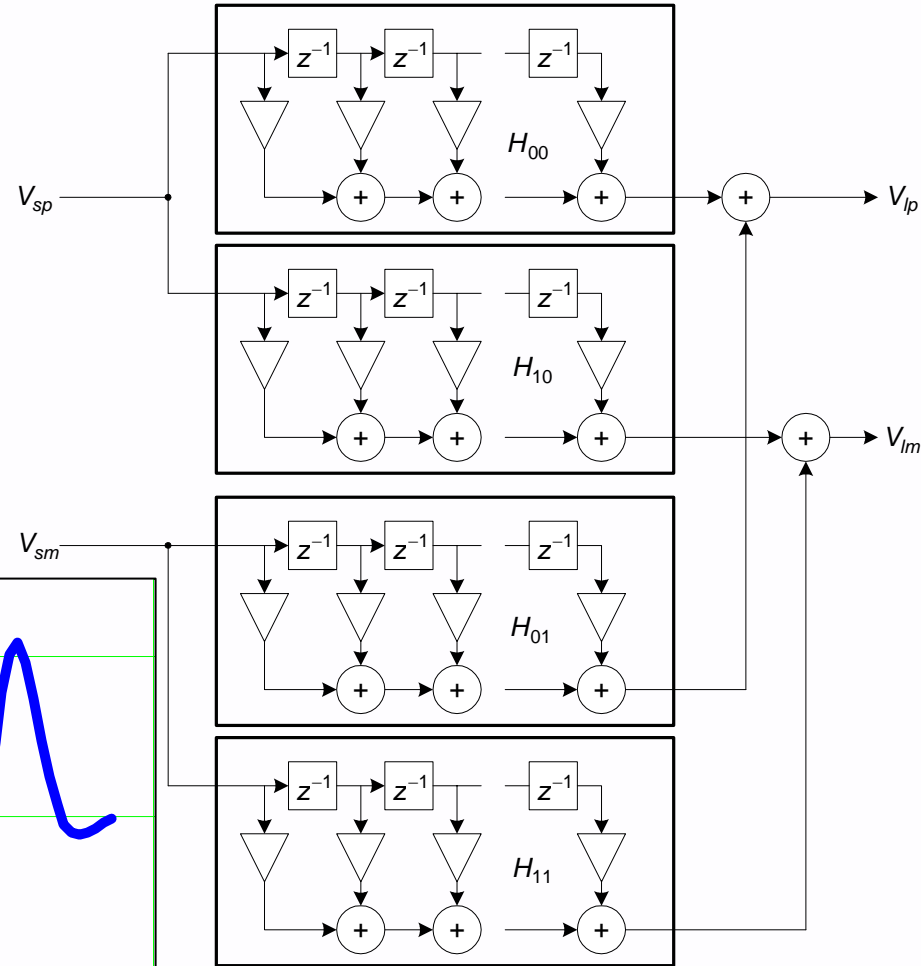
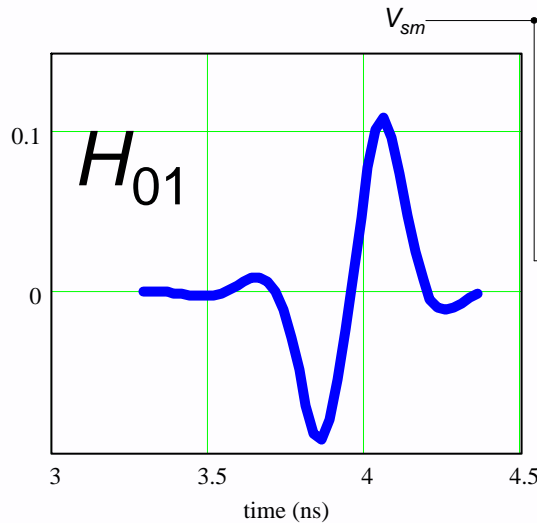
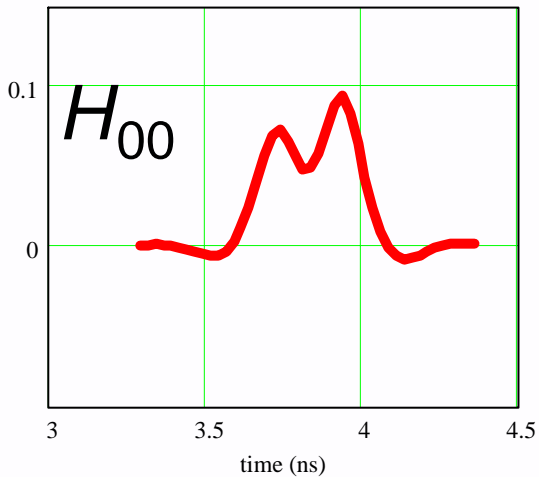
$$\begin{bmatrix} V_{lp} \\ V_{lm} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{4,0}} & S_{i_{4,1}} \\ S_{i_{5,0}} & S_{i_{5,1}} \\ S_{i_{6,0}} & S_{i_{6,1}} \\ S_{i_{7,0}} & S_{i_{7,1}} \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{0,0}} & S_{i_{0,1}} \\ S_{i_{1,0}} & S_{i_{1,1}} \\ S_{i_{2,0}} & S_{i_{2,1}} \\ S_{i_{3,0}} & S_{i_{3,1}} \end{bmatrix}^{-1} \cdot \begin{bmatrix} V_{sp} \\ V_{sm} \end{bmatrix}$$

$$\begin{bmatrix} H_{00} & H_{01} \\ H_{10} & H_{11} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{4,0}} & S_{i_{4,1}} \\ S_{i_{5,0}} & S_{i_{5,1}} \\ S_{i_{6,0}} & S_{i_{6,1}} \\ S_{i_{7,0}} & S_{i_{7,1}} \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} S_{i_{0,0}} & S_{i_{0,1}} \\ S_{i_{1,0}} & S_{i_{1,1}} \\ S_{i_{2,0}} & S_{i_{2,1}} \\ S_{i_{3,0}} & S_{i_{3,1}} \end{bmatrix}^{-1} \quad \begin{bmatrix} H_{00} & H_{01} \\ H_{10} & H_{11} \end{bmatrix} \cdot \begin{bmatrix} V_{sp} \\ V_{sm} \end{bmatrix} = \begin{bmatrix} V_{lp} \\ V_{lm} \end{bmatrix}$$

Virtual Probing Filter Structure

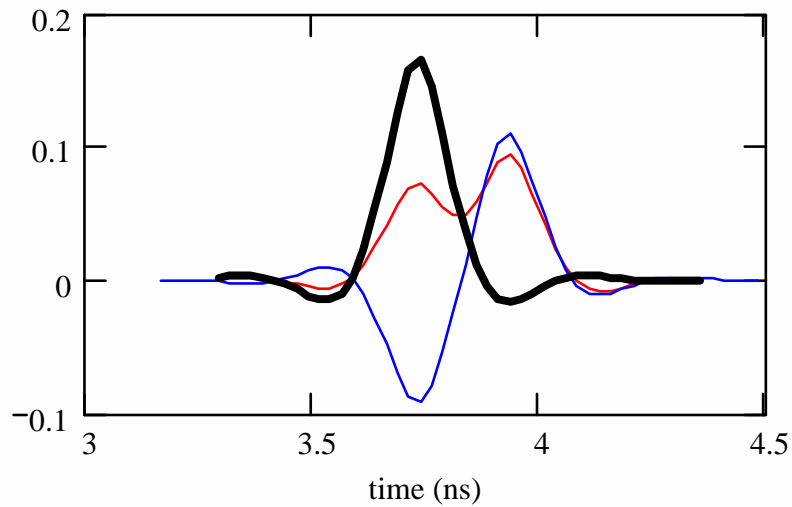


Both filters transmit the common mode in the same polarity, and the differential mode in the opposite polarity.

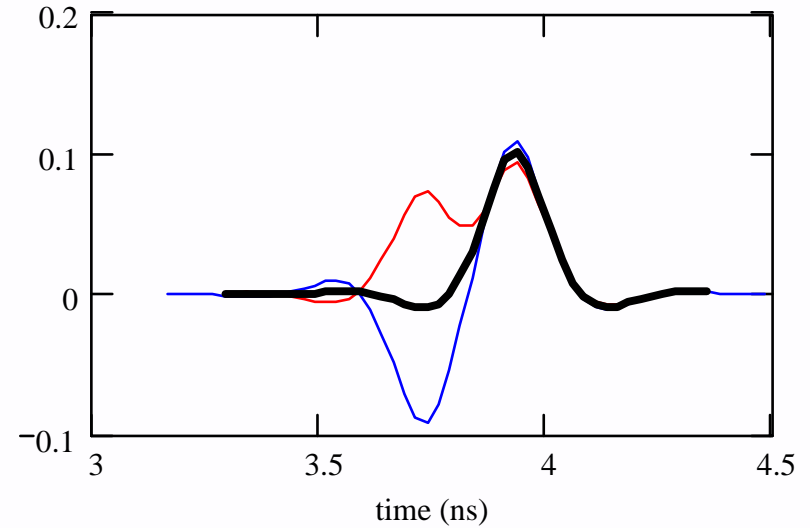


$$\begin{bmatrix} H_{00} & H_{01} \\ H_{10} & H_{11} \end{bmatrix} \cdot \begin{bmatrix} V_{sp} \\ V_{sm} \end{bmatrix} = \begin{bmatrix} V_{lp} \\ V_{lm} \end{bmatrix}$$

Filter Responses Explained



— H00
— H01
— Differential Mode Response



— H00
— H01
— Common Mode Response

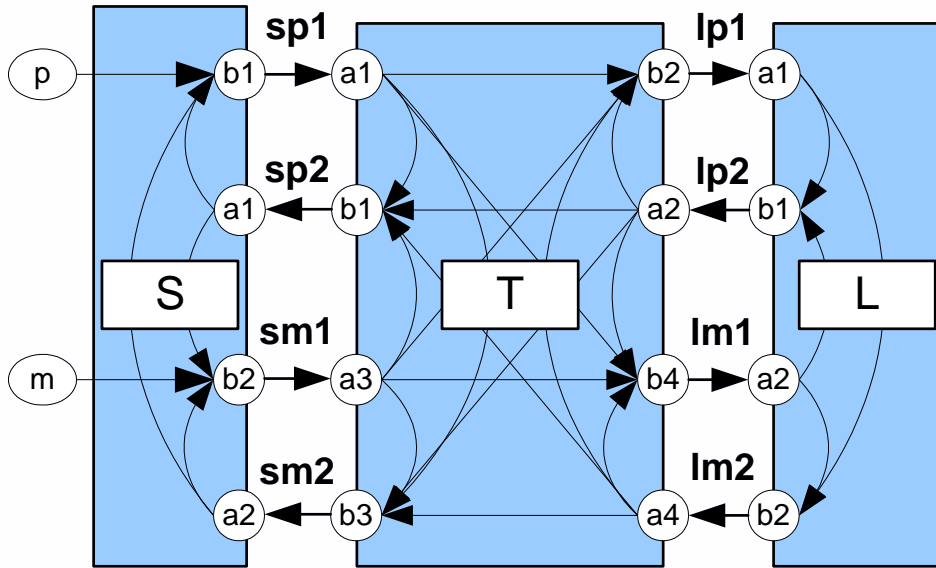
Virtual Probing Agenda

- Setting up Virtual Probing
- System Description Files and Diagrams
- S-parameters and S-parameter files
- Virtual Probing Theory of Operation
- *How it Works Internally*
- Matching Problems to Diagrams
- TinyCAD
- Summary

Internal Steps

- Set up a ***System Description*** which is an array of devices, each device having S-parameters and an array of ports, each port containing a stimuli, an A node and a B node.
- Set up the equations corresponding to the system description and solve them.
- Convert the solutions into transfer functions and then into filters.

Table Equivalent of System Description



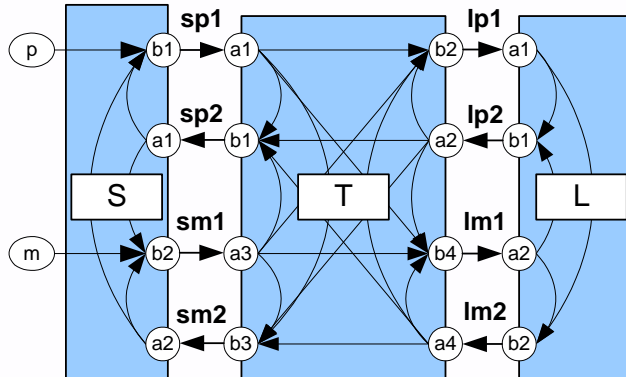
0 S	0	A	sp2
		B	sp1
		S	p
	1	A	sm2
		B	sm1
		S	m
1 T	0	A	sp1
		B	sp2
		S	
	1	A	sm1
		B	sm2
		S	
	2	A	lp2
		B	lp1
		S	
	3	A	lm2
		B	lm1
		S	
2 L	0	A	lp1
		B	lp2
		S	
	1	A	lm1
		B	lm2
		S	

Compact, but Time Consuming Code

```
Array < ComplexMatrix > Sinv(spsd[0].S().Elements());
// build S (and actually Sinv)
for (int n=0; n < spsd[0].S().Elements(); ++n)
{ // for each frequency element
  ComplexMatrix S(ports,ports,COMPLEX(0.0));
  for (int d=0; d < spsd.Elements(); ++d)
  { // for each device...
    for (int p=0; p < spsd[d].Elements(); ++p)
    { // for each port in the device...
      // calculate the row in S based on the B node connection
      int r=Index(spsd[d][p].BNodeName(),N);
      S[r][r] = 1.0;
      //M[r] = Devices[d][p].StimName();
      for (int c=0; c < spsd[d].Elements(); ++c)
      {
        S[r][Index(spsd[d][c].ANodeName(),N)] = -spsd[d].S()[n][p][c];
      }
    }
  }

  Sinv[n] = ComplexMatrix::Inverse(S);
}
```

How System Equations are Generated



$$\begin{bmatrix}
 1 & 0 & -sS_{11} & -sS_{12} & 0 & 0 & 0 & 0 \\
 0 & 1 & -sS_{21} & -sS_{22} & 0 & 0 & 0 & 0 \\
 -sT_{11} & -sT_{12} & 1 & 0 & 0 & 0 & -sT_{13} & -sT_{14} \\
 -sT_{21} & -sT_{22} & 0 & 1 & 0 & 0 & -sT_{23} & -sT_{24} \\
 -sT_{31} & -sT_{32} & 0 & 0 & 1 & 0 & -sT_{33} & -sT_{34} \\
 -sT_{41} & -sT_{42} & 0 & 0 & 0 & 1 & -sT_{43} & -sT_{44} \\
 0 & 0 & 0 & 0 & -sL_{11} & -sL_{12} & 1 & 0 \\
 0 & 0 & 0 & 0 & -sL_{21} & -sL_{22} & 0 & 1
 \end{bmatrix} \cdot \begin{bmatrix}
 sp_1 \\
 sm_1 \\
 sp_2 \\
 sm_2 \\
 lp_1 \\
 lm_1 \\
 lp_2 \\
 lm_2
 \end{bmatrix} = \begin{bmatrix}
 p \\
 m \\
 0 \\
 0 \\
 0 \\
 0 \\
 0 \\
 0
 \end{bmatrix}$$

0	S	0	A	sp2		
			B	sp1		
			S	p		
	1	S	0	A	sm2	
				B	sm1	
				S	m	
1	T	0	A	sp1		
			B	sp2		
			S			
		1	T	0	A	sm1
					B	sm2
					S	
	2	T	0	A	lp2	
				B	lp1	
				S		
	2	L	0	A	lp1	
				B	lp2	
				S		
1		L	0	A	lm1	
				B	lm2	
				S		

Eye Doctor Summary

- Measuring signal at transmitter guarantees maximum signal fidelity – minimizes measurement error
- Simulating channel and interconnects provides accurate and repeatable measurements
- S-parameters of compliance channel can be defined in specification
- Standard equalizers defined in software allow measurements on closed eyes independent of specific implementations