

Driver Precomp Proposal, Review

00-382r1 31-Oct-00

DC loss of the backplane is much higher, 16 ohms for 15 slot backplane

4 ohms cable DC

500mV strong driver

Paul Aloisi - TI

370

475

495

500

560

620

700

740

800

Millivolt drive

Nominal Voltage

60 - 78% weak

No driver imbalance, matched assertion and negation

66 - 50% weak

Driver Fallback 22%	288.6	370.5	386.1	390	436.8	483.6	546	577.2	624
Driver Fall back 33%	244.2	313.5	326.7	330	369.6	409.2	462	488.4	528
Driver Fall Back 40%	222	285	297	300	336	372	420	444	480
Driver Fall Back 50%	185	237.5	247.5	250	280	310	350	370	400

474.359 mV

560.6061 mV

616.6667 mV

740 Min high drive, for 370 mV

Assuming perfect driver asymmetry

Signals levels below are at the connector of the receiving device, use the numbers with DC loss

No Fall back	14	35	39	40	52	64	80	88	100
Precomp off	-3.02	13.15	16.23	17	26.24	35.48	47.8	53.96	63.2

23% DC loss from cable, connectors and terminators

Worst case, no driver tolerance

35 mV

-5 mV receiver required - Adaptive Active Filter - no eye pattern

Cable roll off to 60% signal -60 mV crosstalk & Noise

Trans FB 22% roll off to 60%	22.0512	45.336	49.7712	50.88	64.1856	77.4912	95.232	104.1024	117.408
Trans FB 33% roll off to 60%	35.7264	62.892	68.0664	69.36	84.8832	100.4064	121.104	131.4528	146.976
Trans FB 40% roll off to 60%	42.564	71.67	77.214	78.6	95.232	111.864	134.04	145.128	161.76
Trans FB 50% roll off to 60%	53.96	86.3	92.46	94	112.48	130.96	155.6	167.92	186.4

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$$(((V+VFB)*.6)-Vfb)*0.77)-60$$

100 mV receiver required, 60 mV Crosstalk and System Noise

Color code

20 mV @ receiver

80 mV @ receiver

100 mV @ receiver

Grey is illegal

Adaptive Active filter required, eye pattern

99-295 wide pulse

Bold Black does not work without Adaptive Active Filter

Purple 20 mV receiver - active Filter

Red 80 mV receiver

Blue 100 mV receiver

Driver Assymetry caclulations

No Fall back - toleranced 10%	-22	-7.3	-4.5	-3.8	4.6	13	24.2	29.8	38.2
Precomp off	-30.74	-19.421	-17.265	-16.726	-10.258	-3.79	4.834	9.146	15.614

Without DC loss

23% DC loss from cable, connectors and terminators

Improved Tolerance driver asymmetry

10%

Cable roll off to 60% signal -60 mV crosstalk & Noise

Weak 78% roll off to 60%	-5.6688	12.765	16.2762	17.154	27.6876	38.2212	52.266	59.2884	69.822
Weak 66% roll off to 60%	8.0064	30.321	34.5714	35.634	48.3852	61.1364	78.138	86.6388	99.39
Weak 60% roll off to 60%	14.844	39.099	43.719	44.874	58.734	72.594	91.074	100.314	114.174
Weak 50% roll off to 60%	26.24	53.729	58.965	60.274	75.982	91.69	112.634	123.106	138.814

-30 mV receiver required - Adaptive Active Filter - no eye pattern

Recommended -100 mV Adaptive Active Filter

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$$DC \& AC Loss (((0.77*((V*.9)-23))+(Vfb*.77))*0.6)-(Vfb*.77))-60$$

45 mV receiver needed minimum

Drive tolerance calculation

Seagate numbers limits configuration

Weak 78% roll off to 70%	40.4234	72.44	78.5384	80.063	98.3582	116.6534	141.047	153.2438	171.539
Weak 66% roll off to 70%	50.6798	85.607	92.2598	93.923	113.8814	133.8398	160.451	173.7566	193.715
Weak 60% roll off to 70%	55.808	92.1905	99.1205	100.853	121.643	142.433	170.153	184.013	204.803
Weak 50% roll off to 70%	64.355	103.163	110.555	112.403	134.579	156.755	186.323	201.107	223.283

23% DC loss from cable, connectors and terminators

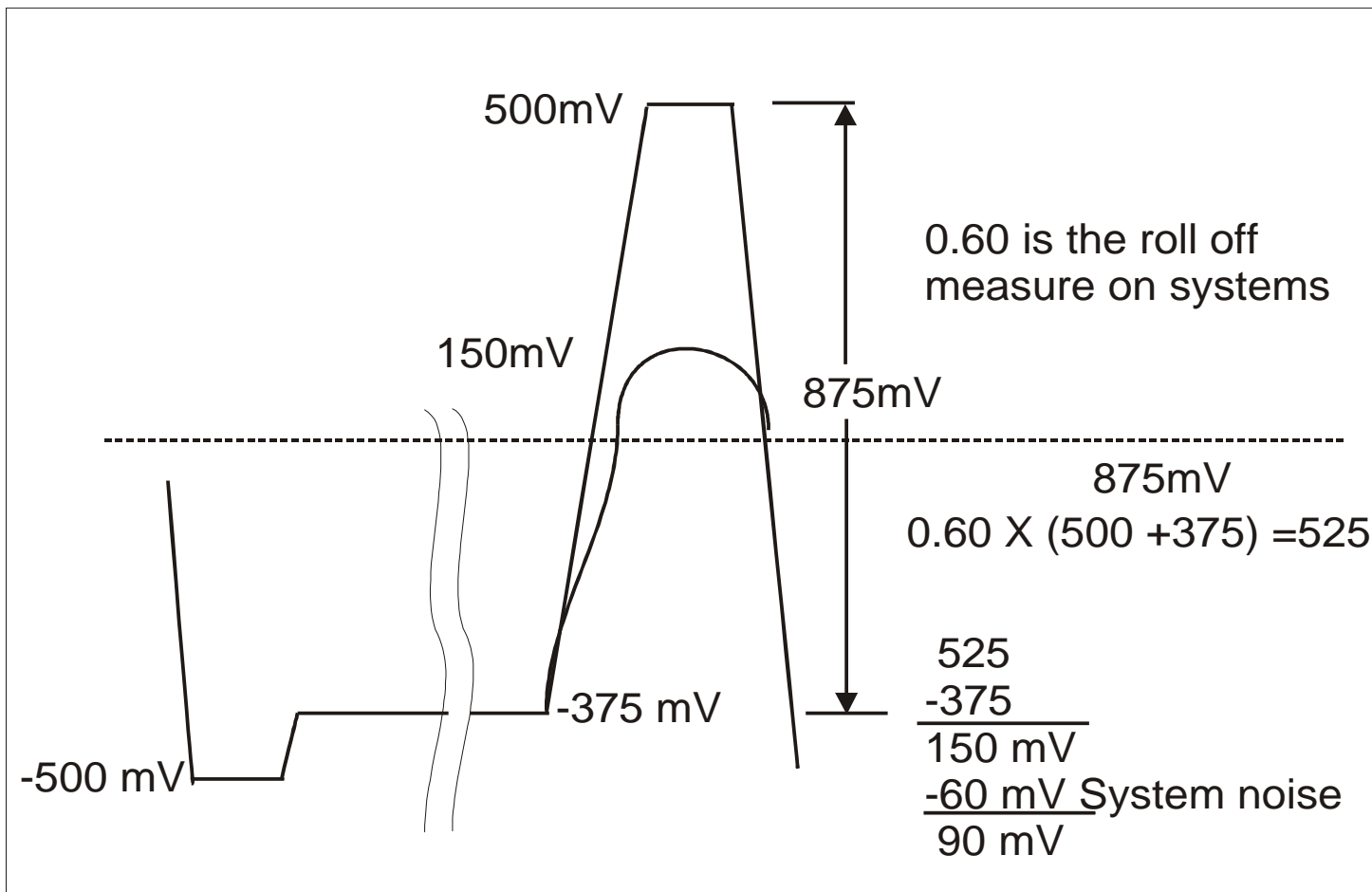
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$$DC \& AC Loss (((0.77*((V*.9)-23))+(Vfb*.77))*0.7)-(Vfb*.77))-60$$

100 mV Receiver needed for minimum



SPI-3

100 mV @ receiver **100** **100** **100** **100** **100** **100** **100** **100** **100** **100 mV**
Minimum signal at the receiver

Tolerance driver

SPI-2/3 driver 320 340 400 427 485 500 600 700 800 Millivolt drive

Cable roll off to 85% signal

Trans FB min to assert (85%) 122.18 130.91 157.1 168.8855 194.2025 200.75 244.4 288.05 331.7 mV signal at the receiver minus cable loss

SPI-2/3 calculations **94.853** **102.2735** **124.535** **134.5527** **156.0721** **161.6375** **198.74** **235.8425** **272.945** 15% cable loss

Should be SPI-2/3 **76.635** **83.1825** **102.825** **111.6641** **130.6519** **135.5625** **168.3** **201.0375** **233.775** 25% cable & system loss

Should be SPI-2/3 **125.7702** **135.0949** **163.069** **175.6573** **202.699** **209.6925** **256.316** **302.9395** **349.563** 23% DC and 5% AC cable & system loss

Additional Data on backplane losses shows that SPI-2 and SPI-3 should have been 28% loss.

Minimum drive level did not work in the worst case.